

INTELLIGENT USB LCD MODULE SPECIFICATIONS



Crystalfontz Model Number	CFA533-YYH-KU
Hardware Version	Revision 1.0, March 2010
Firmware Version	Revision u1.0, April 2010
Data Sheet Version	Revision 2.1, January 2011
Product Pages	http://www.crystalfontz.com/product/CFA533-YYH-KU

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CONTENTS

MAIN FEATURES	-
Comparison to CFA633	9
Features	9
Module Classification Information	
Ordering Information	
MECHANICAL SPECIFICATIONS	
Physical Characteristics	12
LCD Module Outline Drawings	13
Jumper Locations and Functions	
Keypad Detail Drawing	
Panel Mounting Application Cutout Drawing	17
OPTICAL CHARACTERISTICS	
ELECTRICAL SPECIFICATIONS	
System Block Diagram	
Supply Voltages and Current	
Temperature and Humidity Ratings	20
ESD (Electro-Static Discharge) Specifications	21
CONNECTION INFORMATION	
Overview of Connection Information	
Standard (5+v) and Data Communications Connections	
1. Standard (+5v) Power Supply and USB Data Communications through USB Connector	
2. Standard (+5v) Connection through J_PWR Connector	24
3. Standard (+5v) Connection through J8 Connector	25
ATX Power Supply and Control Connection for Host Power Sense	25
ATX Power Supply Connection	
ATX Control Connections for Host Power Sense	
ATX Keypad Control	
GPIO Connections	
Dallas Semiconductor 1-Wire Device Connections for Optional Accessories	
Temperature Sensors	
Other 1-Wire Devices	
HOST COMMUNICATIONS	
Packet Structure	
About Handshaking	
Report Codes	
0x80: Key Activity	
0x82: Temperature Sensor Report	
Command Codes	
0 (0x00): Ping Command	
1 (0x01): Get Hardware & Firmware Version	
2 (0x02): Write User Flash Area	
3 (0x03): Read User Flash Area	
4 (0x04): Store Current State as Boot State	
5 (0x05): Reboot CFA533, Reset Host, or Power Off Host	38

CONTENTS, CONTINUED

6 (0x06): Clear LCD Screen	
7 (0x07): Set LCD Contents, Line 1	
8 (0x08): Set LCD Contents, Line 2	
9 (0x09): Set LCD Special Character Data	
10 (0x0A): Read 8 Bytes of LCD Memory	
11 (0x0B): Set LCD Cursor Position	
12 (0x0C): Set LCD Cursor Style	
13 (0x0D): Set LCD Contrast	
14 (0x0E): Set LCD & Keypad Backlight	
18 (0x12): Read DOW Device Information	
19 (0x13): Set Up Temperature Reporting	
20 (0x14): Arbitrary DOW Transaction	
21 (0x15): Set Up Live Temperature Display	
22 (0x16): Send Command Directly to the LCD Controller	46
23 (0x17): Configure Key Reporting	
24 (0x18): Read Keypad, Polled Mode	
28 (0x1C): Set ATX Switch Functionality	48
29 (0x1D): Enable/Feed Host Watchdog Reset	
30 (0x1E): Read Reporting/ATX/Watchdog (debug)	50
31 (0x1F): Send Data to LCD	
33 (0x21): Set Baud Rate	
34 (0x22): Set/Configure GPIO	
35 (0x23): Read GPIO Pin Levels and Configuration State	53
CHARACTER GENERATOR ROM (CGROM)	
LCD MODULE RELIABILITY AND LONGEVITY	
Module Reliability	
Module Longevity (EOL / Replacement Policy)	
CARE AND HANDLING PRECAUTIONS	
APPENDIX A: QUALITY ASSURANCE STANDARDS	
APPENDIX B: SAMPLE CODE AND CALCULATING THE CRC	
Sample Code	
Algorithms to Calculate the CRC	
Algorithm 1: "C" Table Implementation	
Algorithm 2: "C" Bit Shift Implementation	
Algorithm 2B: "C" Improved Bit Shift Implementation	
Algorithm 3: "PIC Assembly" Bit Shift Implementation	
Algorithm 4: "Visual Basic" Table Implementation	70
Algorithm 5: "Java" Table Implementation	
Algorithm 6: "Perl" Table Implementation	
Algorithm 7: For PIC18F8722 or PIC18F2685	
APPENDIX C: CONNECTING A DS2450 1-WIRE QUAD A/D CONVERTER	77



LIST OF FIGURES

Figure 1.	CFA533-YYH-KU Module Outline Drawing (two pages below)	13
Figure 2.	Jumper Locations and Functions	15
Figure 3.	Keypad Detail Drawing	16
Figure 4.	Panel Mounting Application Cutout Drawing	17
Figure 5.	Definition of 6:00 O'clock and 12:00 O'clock Viewing Angles	18
Figure 6.	System Block Diagram	19
Figure 7.	CFA533-YYH-KU Current Usage	21
Figure 8.	Standard (+5v) Power Supply and USB Data Communications through USB Connector	23
Figure 9.	Standard +(5v) Connection through J_PWR Connector	24
Figure 10.	Standard (+5v) Connection through J8 Connector	25
Figure 11.	ATX Power Supply and Host Power Sense through PWR on USB Connector via JPUSBSENSE	26
Figure 12.	ATX Host Power Sense through +5v on J_PWR Connector	27
Figure 13.	ATX Host Power Sense through GPIO[1] on J8 Connector	28
Figure 14.	ATX Power Supply and Control Using Crystalfontz WR-PWR-Y14 Cable	29
Figure 15.	Location of GPIO Connections, Resistors, and J_DOW	32
Figure 16.	Character Generator ROM (CGROM)	55



REVISION HISTORY

HARDWARE				
2010/06/06	 Hardware version: v1.0 (revision number has not changed) Changes: We are transitioning to an improved keypad from "10.5" millimeters to "12.00" millimeters high. See <u>PCN 10282</u>. 			
2010/03/18	 Hardware version: v1.0 Changes since hardware version (v0.1): As the inventory of hardware version v0.1 depletes, we are phasing in the improved v1.0. The v1.0 should be a drop-in replacement for any v0.1 application. 1. Added a JPUSBSENSE jumper to help user configuration. See Jumper Locations and Functions. 2. Changed JPFG to RFG. RFG connects 1MΩ between logic ground and frame ground. See Jumper Locations and Functions. 3. PCB layout changes: Added more breaks to the frame ground (FG) trace that surrounds the board so there is not a loop. Added masking on FG trace where connectors may be hand soldered to ease assembly. Moved vias from under the zebra near the ends of the bezel to assure no shorts between the vias and the bezel. Made mounting hole annular ring (pads) larger to avoid component damage by tools during assembly. Resistors are loaded wherever needed. 			
2007/12/31	Hardware version: v0.1 New module.			

	FIRMWARE				
2010/05/15	Current firmware version: u1.0 Changes since last version (u0.x \rightarrow u1.0): Firmware version now matches all modules that are hardware version v1.0.				
2009/04/15	Firmware version: u0.x→u1.0 New firmware.				



DATA SHEET			
2011/01/17	 Current Data Sheet version: v2.1 Changes since Data Sheet version (v2.0): In command <u>4 (0x04): Store Current State as Boot State (Pg. 37)</u>, added Errata Note. Please read this note. 		

	DATA SHEET (Continued)
2010/12/16	 Data Sheet version: v2.0 Changes since Data Sheet version (v1.1): Wherever listed or shown, changed keypad from "10.5" millimeters to "12.00" millimeters high. This transition started 2010/6/06. See PCN 10282. Wherever listed, deleted dash (-*) from module part numbers to match how they now appear on our website without the dash (-*). In Features (Pg. 9), added "RoHS compliant", "Factories are ISO certified", and that materials are in compliance with EU Directive "REACH". In Ordering Information (Pg. 11) section. Changed part numbers for I²C variants of CFA-533 modules to end in "-KC" instead of "-KI". For I²C variants, deleted note "Semi-custom part number and minimum order may apply." Modules may be ordered through the website using its standard part number, no minimum required. In Prhysical Characteristics (Pg. 12). Changed module depth dimension to include keypad "12.00" millimeters high (formerly 10.5 millimeters high). Module weight increased from "40" grams to "41" grams. Updated information in Jumper Locations and Functions (Pg. 15) due to hardware revision v1.0. Adde a JPUSBENSE jumper to help user configuration. Changed JPFG to RFG RFG connects 1MΩ between logic ground and frame ground. Confirm: mention this for all interfaces? Added OPTICAL CHARACTERISTICS (Pg. 18) section, with definition of viewing angles. In Temperature and Humidity Ratings (Pg. 20), added Humidity Range specification. Expanded and improved information on all power and control connections. See CONNECTION INFORMATION (Fg. 21), particularly Beccuse in hardware version 1.0, resistors are loaded by default, all references to "resistors not loaded" were removed. In command 8(00.08); SetLCD Contents. Line 2 (Pg. 40), corrected screen display text from data [0] = column (0-15 valid) data [1] = row (0-1 valid) data [1] = row (0-1 valid) data [1] = row (0-1 valid) data [1] = row (0-1



DATA SHEET (Continued)				
2010/12/16	 In <u>APPENDIX B: SAMPLE CODE AND CALCULATING THE CRC (Pg. 65)</u>, In <u>Sample Code (Pg. 65)</u>, added hyperlinks to free downloadable sample code available on our website. In sample code for <u>Algorithm 1: "C" Table Implementation (Pg. 65)</u> and <u>Algorithm 2: "C" Bit Shift Implementation (Pg. 66)</u>, added typedefs for "ubyte" and "word". Added sample code <u>Algorithm 7: For PIC18F8722 or PIC18F2685 (Pg. 74)</u>. In addition to list above, wherever needed, made minor changes in text and illustrations to improve clarity. 			
2009/06/20	 Data Sheet version: v1.1 Changes since last revision (v1.0): Note about semi-custom part number and minimum order in Ordering Information table was deleted. I²C can be ordered directly from our website. Section on ATX POWER SUPPLY POWER AND CONTROL CONNECTIONS modified for clarification. For command 33 (0x21): Set Baud Rate, corrected data[1] to data[0]. In section on POWER CONNECTIONS THROUGH USB, corrected part number link for the Tyco Electronics/Amp connector. Corrected explanation for CHARACTER GENERATOR ROM (CGROM). Minor wording and formatting changes. 			
2009/04/15	Data Sheet version: v1.0 New Data Sheet.			

The Fine Print

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MAIN FEATURES

COMPARISON TO CFA633

If your project does not need the fan connections, the CFA533 series is an economical replacement for the CFA633 series. In November 2010, we issued a Technical Bulletin that describes the differences between the CFA533 series and three versions of the CFA633 series. Please see <u>Part Change Notice #10291</u>.

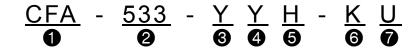
FEATURES

- I6 characters x 2 lines LCD with keypad and high-level interface. Will fit nicely in a 1U rack mount case (35 mm overall height).
- Only a single supply is needed. Wide power supply voltage range (V_{DD} = +3.3v to +5.0v) is perfect for embedded systems.
- Backlight and contrast are fully voltage compensated over the power supply range. No adjustments to the contrast setting or backlight brightness are needed.
- The CFA533 series is mechanically similar to the the <u>CFA633</u> series. The CFA533 series command set is compatible with the <u>CFA633</u> series. The CFA533 can be used as a "drop-in" replacement for most <u>CFA633</u> series applications that do not need fan capabilities.
- □ Full-speed USB interface.
- Edge-lit yellow-green LED backlight with positive yellow-green STN LCD. Displays dark character s on yellow background. Integrated yellow LED backlit 6-button translucent silicon keypad.
- Desitive mode display is sunlight readable and also readable in dark areas.
- □ Fully decoded keypad: any key combination is valid and unique.
- □ Robust packet-based communications protocol with 16-bit CRC.
- Nonvolatile memory capability (EEPROM):
 - Customize the "power-on" display settings.
 - 16-byte "scratch" register for storing data such as IP address, netmask, system serial number . . .
- Optional capabilities. Crystalfontz can make these modifications for you. A semi-custom part number and minimum order may apply.
 - ATX power supply control functionality allows the buttons on the CFA533-YYH-KU to replace the Power and Reset switches on your system, simplifying front panel design. The ATX functionality can also implement a hardware watchdog that can reset host system on host software failure.
 - Temperature monitoring: up to 32 channels at up to 0.5 degrees Celsius with absolute accuracy (using optional connector and Crystalfontz <u>WR-DOW-Y17</u> cable with Dallas 1-Wire sensor).
 - "Live Display" shows up to four temperature readings without host intervention, allowing temperatures to be shown immediately at boot, even before the host operating system is loaded.
 - RS-232 to Dallas Semiconductor 1-Wire bridge functionality allows control of other 1-Wire compatible devices such as ADC, voltage monitoring, current monitoring, RTC, GPIO, counters, and identification/encryption. (Additional hardware required.)
- □ RoHS compliant.
- □ Factories have ISO certification.
- Product materials are in compliance with the regulations related to the EU Directive 2006/121/EC for Registration, Evaluation, Authorization and Restriction of Chemicals (REACH).



If you need a CE or MET (UL type) approved LCD module, please see our XES635 USB series (<u>http://www.crystal-fontz.com/product/XES635BK-YYE-KU.html</u>, <u>http://www.crystalfontz.com/product/XES635BK-TMF-KU.html</u>, or <u>http://www.crystalfontz.com/product/XES635BK-TFE-KU.html</u>. The CFA533-YYH-KU does not have CE or MET (UL type) certification because it is not an end product. The module requires power and communications from another system in order to operate.

MODULE CLASSIFICATION INFORMATION



0	Brand	Crystalfontz America, Inc.		
0	Model Identifier	533		
0	Backlight Type & Color	Y – LED, yellow-green		
4	Fluid Type, Image (positive or negative), & LCD Glass Color	Y – STN, positive yellow-green		
6	Polarizer Film Type, Temperature Range, & View Angle (O 'Clock)	H – Transflective, Wide Temperature Range ¹ , 6:00		
6	Special Code 1	K – Manufacturer's code		
1	Special Code 2	U – USB interface		
^{1}W	¹ Wide Temperature Range is -20°C minimum to +70°C maximum			



ORDERING INFORMATION

PART NUMBER	FLUID	LCD GLASS COLOR	IMAGE	POLARIZER FILM	BACKLIGHT COLOR/TYPE
CFA533-YYH-KU (USB)	STN	yellow- green	positive	transflective	LCD: yellow-green edge LED Keypad: yellow-green LEDs
CFA533-TMI-KC (I ² C)	STN	blue	negative	transmissive	LCD: white edge LEDs Keypad: blue LEDs
CFA533-TMI-KL ("logic-level" RS-232)	STN	blue	negative	transmissive	LCD: white edge LEDs Keypad: blue LEDs
CFA533-TMI-KS ("full swing" RS-232)	STN	blue	negative	transmissive	LCD: white edge LEDs Keypad: blue LEDs
CFA533-TMI-KU (USB)	STN	blue	negative	transmissive	LCD: white edge LEDs Keypad: blue LEDs
CFA533-YYH-KC (l ² C)	STN	yellow-green	positive	transflective	LCD: yellow-green edge LEDs Keypad: yellow-green LEDs
CFA533-YYH-KL ("logic-level" RS-232)	STN	yellow-green	positive	transflective	LCD: yellow-green edge LEDs Keypad: yellow-green LEDs
CFA533-YYH-KS ("full swing" RS-232)	STN	yellow-green	positive	transflective	LCD: yellow-green edge LEDs Keypad: yellow-green LEDs



MECHANICAL SPECIFICATIONS

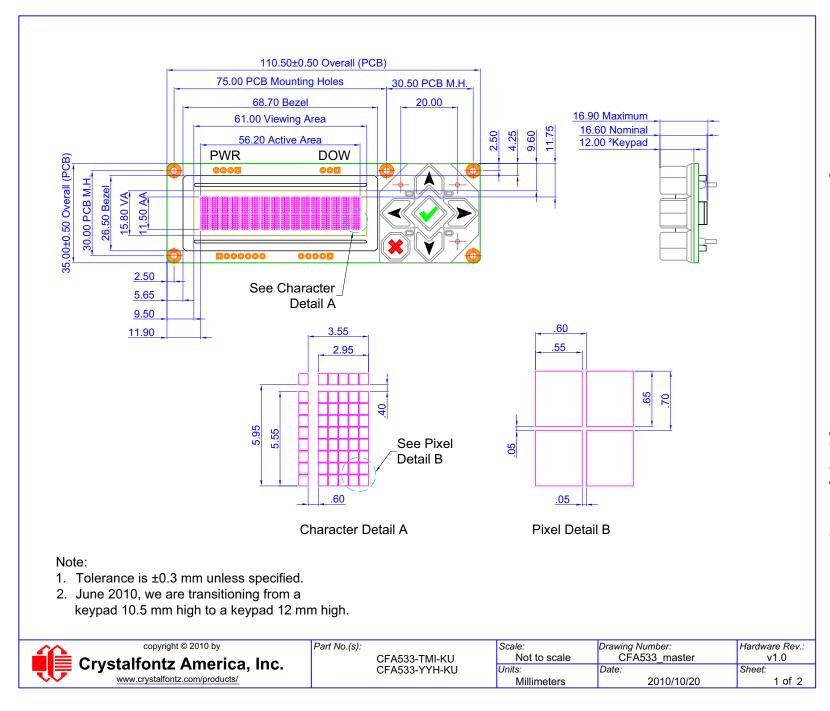
PHYSICAL CHARACTERISTICS

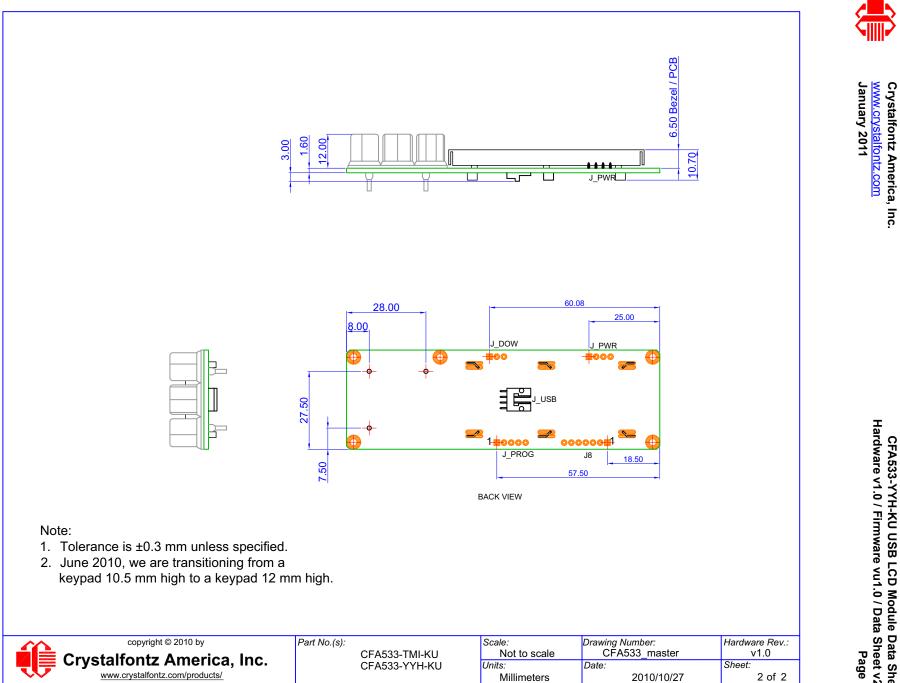
ITEM	SIZE
LCD Module Overall Dimensions	
Width and Height	110.5 (W) x 35.0 (H)
Depth with Keypad	16.60 mm nominal 16.90 mm maximum
Viewing Area	61.0 (W) x 15.8 (H) mm
Active Area	56.2 (W) x 11.5 (H) mm
Character Size	2.95 (W) x 5.55 (H) mm
Character Pitch	3.55 (W) x 5.95 (H) mm
Pixel Size	0.55 (W) x 0.65 (H) mm
Pixel Pitch	0.60 (W) x 0.70 (H) mm
Keystroke Travel (approximate)	2.4 mm
Weight	41 grams (typical)



LCD MODULE OUTLINE DRAWINGS

Figure 1. CFA533-YYH-KU Module Outline Drawing (two pages below)





CFA533-YYH-KU USB LCD Module Data Sheet Hardware v1.0 / Firmware vu1.0 / Data Sheet v2.1 Page 14



JUMPER LOCATIONS AND FUNCTIONS

The CFA533-YYH-KU has thirteen jumpers. Not all jumpers are used by all interfaces. Jumpers may be closed by melting a ball of solder across their gap. You may re-open the jumpers by removing the solder. Use solder wick to remove solder.

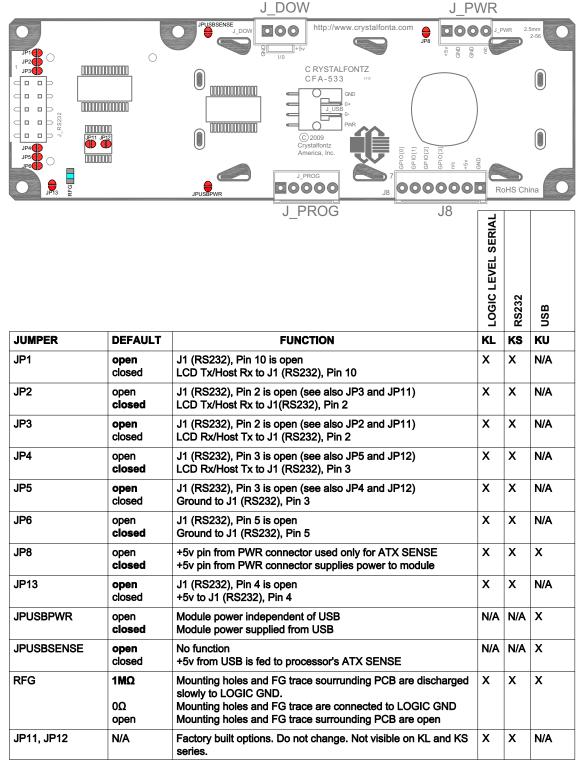
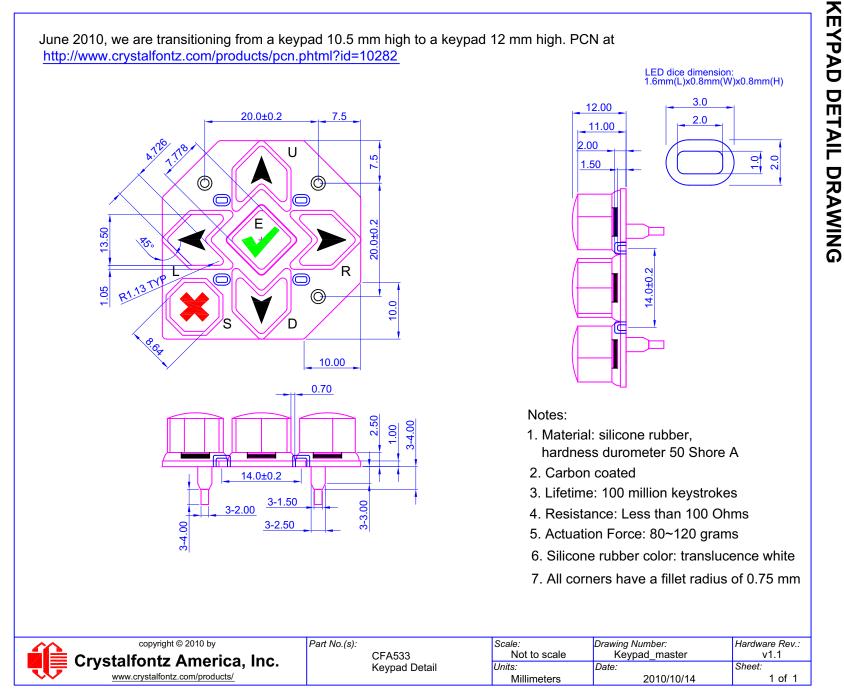
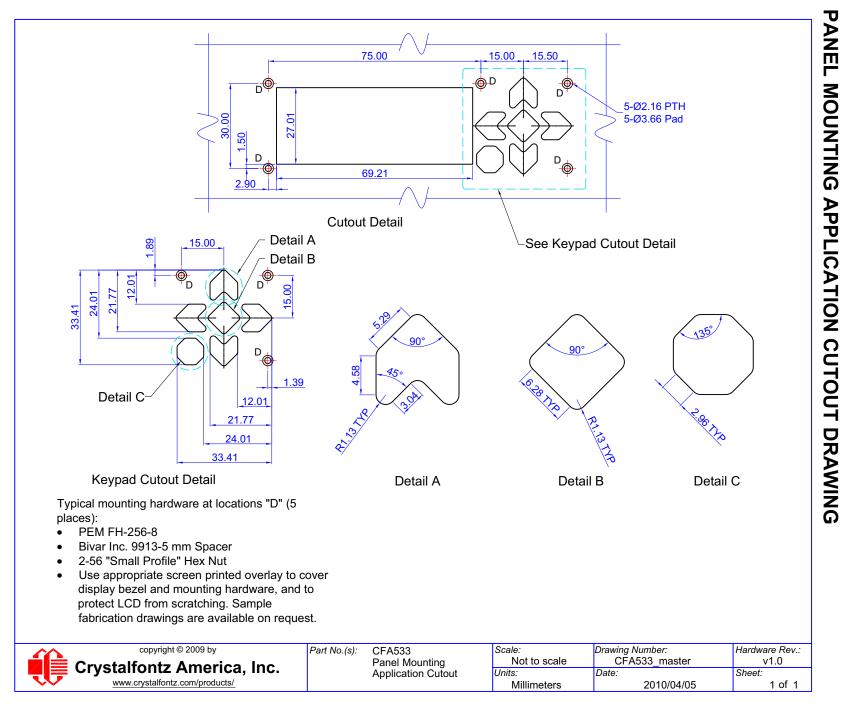


Figure 2. Jumper Locations and Functions





CFA533-YYH-KU USB LCD Module Data Sheet Hardware v1.0 / Firmware vu1.0 / Data Sheet v2.1 Page 17

January 2011

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OPTICAL CHARACTERISTICS

Viewing Direction 6 o'clock

Definition of 6 O'clock and 12:00 O'clock Viewing Angles

This LCD module has a 6:00 o'clock viewing angle. A 6:00 o'clock viewing angle is a bottom viewing angle like what you would see when you look at a cell phone or calculator. A 12:00 o'clock viewing angle is a top viewing angle like what you would see when you look at the gauges in a golf cart or airplane.

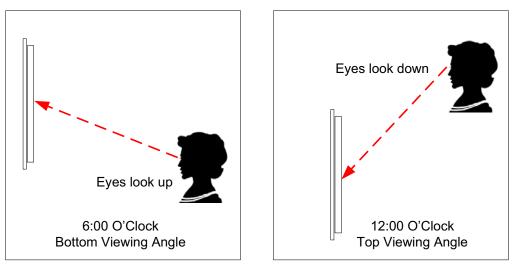
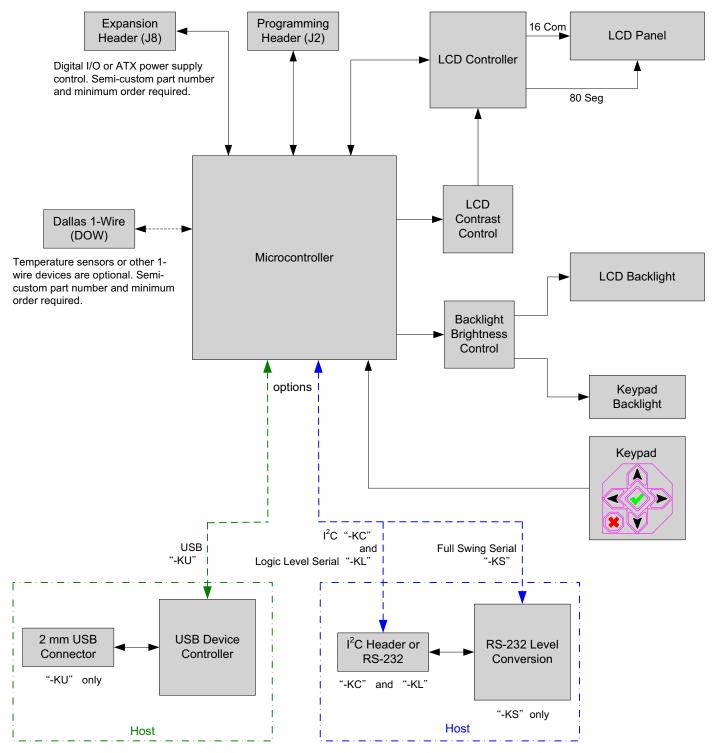


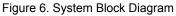
Figure 5. Definition of 6:00 O'clock and 12:00 O'clock Viewing Angles



ELECTRICAL SPECIFICATIONS

SYSTEM BLOCK DIAGRAM







SUPPLY VOLTAGES AND CURRENT

DRIVING METHOD	SPECIFICATION		
Duty	1/16		

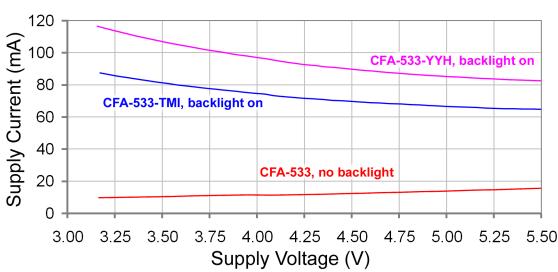
SUPPLY VOLTAGE	MINIMUM	MAXIMUM
Power Supply Voltage (V _{DD})	+3.3v	+5.5v
Pull-in Voltage		+3.2v
Drop-out Voltage		+3.0v

TYPICAL CURRENT CONSUMPTION	SPECIFICATION	
+5v for logic (LCD + microcontroller)	< 20mA	
+5v for logic (LCD + microcontroller) + YYH backlight	< 120mA	

GPIO CURRENT LIMITS	SPECIFICATION		
Sink	25 mA		
Source	10 mA		

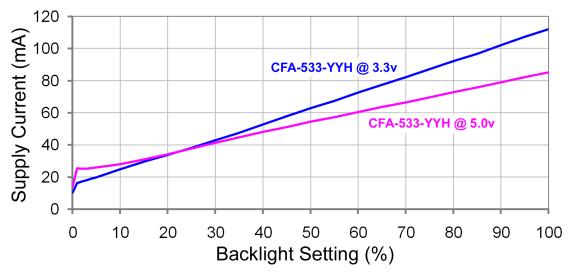
TEMPERATURE AND HUMIDITY RATINGS

ABSOLUTE MAXIMUM RATINGS	SYMBOL	MINIMUM	MAXIMUM
Operating Temperature	T _{OP}	0°C	+50°C
Storage Temperature	T _{ST}	-10°C	+60°C
Humidity Range (noncondensing)	RH	10%	90%



CFA 533 supply current vs supply voltage (typical)







ESD (ELECTRO-STATIC DISCHARGE) SPECIFICATIONS

The circuitry is industry standard CMOS logic and susceptible to ESD damage. Please use industry standard antistatic precautions as you would for any other static sensitive devices such as expansion cards, motherboards, or integrated circuits. Ground your body, work surfaces, and equipment.



CONNECTION INFORMATION

OVERVIEW OF CONNECTION INFORMATION

This section describes your choices of methods to connect power and host power sense to the LCD module. The section also describes connections for optional accessories.

The host power supply can power the CFA533-YYH-KU in one of two ways:

- 1. Standard: This is the basic method to supply power to the module ("non-ATX").
- 2. ATX: This method supplies power to the module and has power on, power off, and reset functionality.

For your convenience, here are links to the connection descriptions:

Standard (5+v) and Data Communications Connections (Pg. 22)

- 1. Standard (+5v) Power Supply and USB Data Communications through USB Connector (Pg. 23)
- 2. Standard (+5v) Connection through J_PWR Connector (Pg. 24)
- 3. Standard (+5v) Connection through J8 Connector (Pg. 25)

ATX Power Supply and Control Connection for Host Power Sense (Pg. 25)

ATX Power Supply Connection (Pg. 25)

- 1. Host Power Sense through PWR on USB Connector via JPUSBSENSE (Pg. 26)
- 2. Host Power Sense through +5v on J_PWR Connecter (Pg. 27)
- 3. Host Power Sense through GPIO[1] on J8 Connector (Pg. 28)
- ATX Keypad Control (Pg. 30)

GPIO Connections (Pg. 31)

Dallas Semiconductor 1-Wire Device Connections for Optional Accessories (Pg. 32) <u>Temperature Sensors (Pg. 32)</u> <u>Other 1-Wire Devices (Pg. 33)</u>

In the sections listed above, we describe which jumpers, if any, must be opened or closed for the different connection methods. A helpful reference is <u>Jumper Locations and Functions (Pg. 15</u>). The table lists the open/close defaults for all jumpers.

STANDARD (5+V) AND DATA COMMUNICATIONS CONNECTIONS

For a standard power connection from a host to the CFA533-YYH-KU, choose one of the three methods described below.

- 1. Standard (+5v) Power Supply and Data Communications through USB Connector
- 2. Standard (+5v) Connection through J_PWR Connector
- 3. Standard (+5v) Connection through J8 Connector



1. Standard (+5v) Power Supply and USB Data Communications through USB Connector

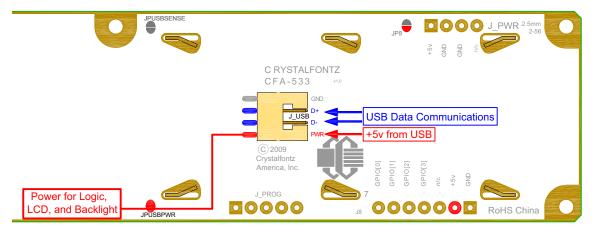


Figure 8. Standard (+5v) Power Supply and USB Data Communications through USB Connector

By using the USB connector, the CFA533-YYH-KU requires only this one connection to the host for both data communications and power supply.

JUSBPWR is closed by default. This allows the USB interface to control the power to the LCD module. When using this connection method, the CFA533-YYH-KU will stay powered off through the host's boot cycle and will only power up after the host's USB subsystem is fully powered up. This is normal behavior.

In order to keep the CFA533-YYH-KU as thin as possible, the CFA533-YYH-KU uses a very low profile 2 mm latching polarized connector for USB connection.

Crystalfontz Cables for USB Connection

Crystalfontz sells two cables that make the connection between the CFA533-YYH-KU and the host.

1. The <u>WR-USB-Y03</u> (6-foot) has the mating 2 mm connector on one end and a standard "USB A" on the other end.

2. The <u>WR-USB-Y11</u> (27-inch) has the mating 2 mm connector on one end and standard single pin connectors on the opposite end. These single pin connectors are suitable to plug directly onto the USB headers typically found on motherboards.

Make Your Own Cable for USB Connection

If you would like to make your own cable, the connector on the CFA533-YYH-KU is: FCI/Berg 95000-004: SMT 2 mm connector, 4-position, polarized

The mating housing and terminals for the cable are:

FCI/Berg 90312-004: Housing, 2 mm connector, 4-position, polarized FCI/Berg 77138-001: Terminal (4 pieces required)

If you want the CFA533-YYH-KU to power up instantly when the host powers up, you can modify the LCD modules or have Crystalfontz modify them for you.



2. Standard (+5v) Connection through J_PWR Connector

By configuring this way, the CFA533-YYH-KU will turn on as soon as +5v is supplied to J_PWR.

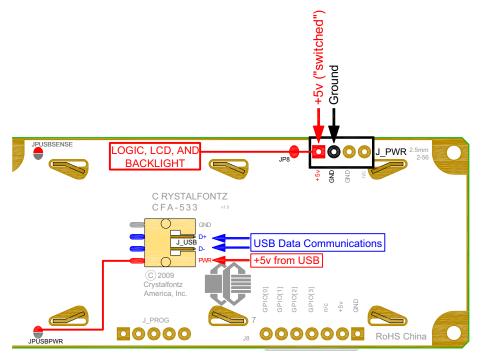


Figure 9. Standard +(5v) Connection through J_PWR Connector

- 1. Open JPUSBPWR. (JPUSBPWR is closed by default.)
- 2. Close JP8. (JP8 is open by default.)
- 3. Install the appropriate connector in J_PWR. (See <u>Tyco Electronics / Amp part number 4-171825-4, Mouser</u> <u>Electronics part number 571-4-171825-4.</u>)
- Connect power from the host's power supply to the CFA533-YYH-KUs J_PWR connector. Use a Crystalfontz cable <u>WR-PWR-Y12</u> or equivalent.



3. Standard (+5v) Connection through J8 Connector

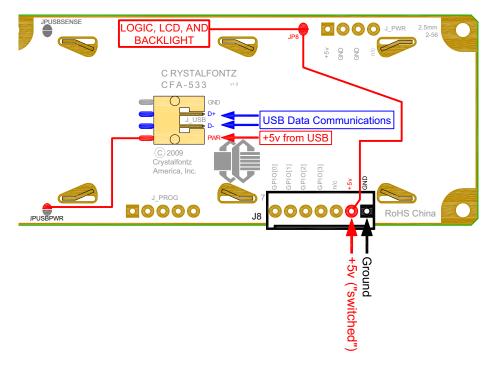


Figure 10. Standard (+5v) Connection through J8 Connector

- 1. Open JPUSBPWR. (JPUSBPWR is closed by default.)
- 2. Close JP8. (JP8 is open by default.)
- 3. Provide power through J8 connector on pin 1 (Ground) and pin 2 (+5v).

Modification by Crystalfontz

We can configure the LCD modules for you by opening JPUSBPWR, closing JP8, and loading your choice of header. The modules will be ready to use in your application without modification by you. For information, please contact technical support (+1-888-206-9720 or email <u>techinfo@crystalfontz.com</u>). We will provide you with a semi-custom part number and pricing. A minimum order quantity may apply.

ATX POWER SUPPLY AND CONTROL CONNECTION FOR HOST POWER SENSE

ATX Power Supply Connection

The CFA533-YYH-KU has the ability to control power on/off and reset functions of an ATX power supply.

NOTE

The GPIO pins used for ATX control must not be configured as user GPIO. If ATX Host Power Sense to LCD module is being used, do not reconfigure the GPIO pins.



For this functionality, the CFA533-YYH-KU is powered from the host's V_{SB} signal (V_{SB} is the standby power which is always-on +5v ATX power supply output).

ATX Control Connections for Host Power Sense

For ATX control, choose one of these three connection methods described below:

- 1. Host Power Sense through PWR on USB Connector via JPUSBSENSE
- 2. Host Power Sense through +5v on J_PWR Connector
- 3. Host Power Sense through GPIO[1] on J8 Connector

1. Host Power Sense through PWR on USB Connector via JPUSBSENSE

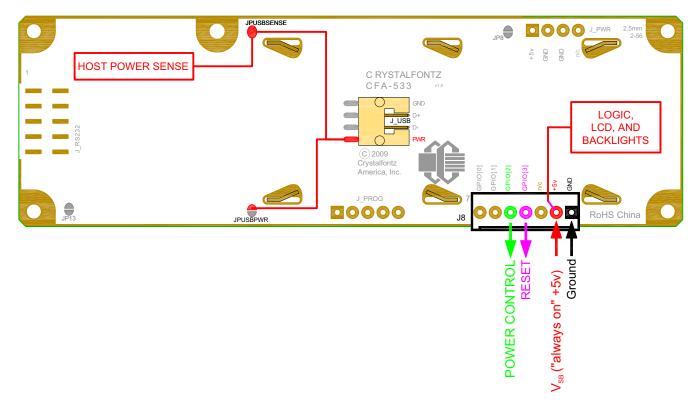


Figure 11. ATX Power Supply and Host Power Sense through PWR on USB Connector via JPUSBSENSE

By default, the pin labeled PWR on the CFA533-YYH-KU's USB connector is electrically connected to +5v pin on the J8 connector through the normally closed JPUSBPWR. If you want to use the CFA533-YYH-KU to do ATX power supply control, open jumper JPUSBPWR, which disconnects the PWR on the USB connector from +5v of the J8 connector. The +5v pin of the J8 connector will function as V_{SB} (standby power which is always-on) to the LCD module. This completes the ATX power supply/host power sense configuration by providing +5v through the 5k Ω 0805 SMT resistor R3 to the microcontroller. See location of R3 in Figure 15. on Pg. 32.

The motherboard's reset switch input is connected to Pin 4 of the CFA533-YYH-KU connector J8 (labeled as GPIO[3]). This pin functions as RESET. The RESET pin is configured as a high-impedance input until the LCD module wants to reset the host. Then it will change momentarily to low impedance output, driving either low or high depending on the setting of RESET_INVERT. (See command <u>28 (0x1C): Set ATX Switch Functionality (Pg. 48)</u>.) This connection is also used for the hardware watchdog.



2. Host Power Sense through +5v on J_PWR Connecter

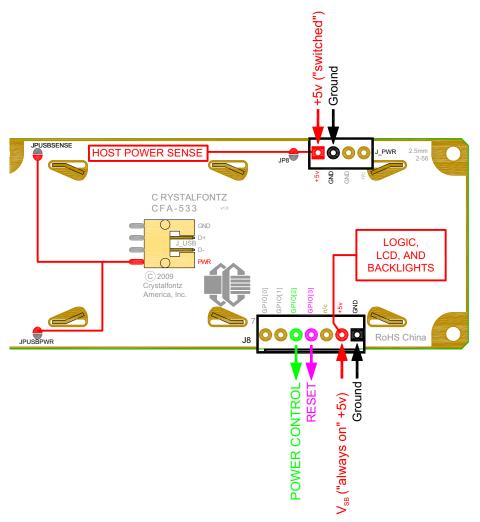


Figure 12. ATX Host Power Sense through +5v on J_PWR Connector

By default, the pin labeled +5v on the CFA533-YYH-KU's J_PWR connector is electrically connected to the +5v pin on the J8 connector through the normally open jumper JP8. If you want to use the CFA533-YYH-KU to do ATX power control, leave jumper JP8 open. The +5v pin of J_PWR will then function as the "Host Power Sense". The +5v pin of the J8 connector will function as V_{SB} (standby power which is always-on) to the LCD module. To complete the ATX power supply/host power sense configuration, open JPUSBPWR so that the LCD module is not powered from the host system's USB connection.



3. Host Power Sense through GPIO[1] on J8 Connector

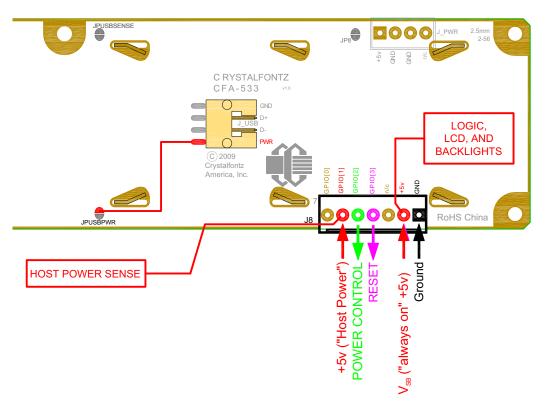


Figure 13. ATX Host Power Sense through GPIO[1] on J8 Connector

When configured, +5v senses on GPIO[1].

The POWER-ON SENSE can be provided through Pin 6 of J8 (GPIO[1]). This option is only provided to allow backwards compatibility for legacy CFA633 applications. R21 is loaded with a $5k\Omega$ 0805 SMT resistor for this functionality.

The motherboard's power switch input is connected to Pin 5 of the CFA533-YYH-KU's connector J8 (labeled as GPIO[2]). This pin functions as POWER CONTROL. The POWER CONTROL pin is configured as a high-impedance input until the LCD module wants to turn the host on or off, then it will change momentarily to low impedance output, driving either low or high depending on the setting of POWER_INVERT. (See command <u>28 (0x1C): Set ATX Switch</u> Functionality (Pg. 48).) For location of R21, see Figure 15. on Pg. 32.

JP8 from connector J_PWR is closed by default. When JP8 is closed, power is connected at J8. The Crystalfontz <u>WR-PWR-Y14</u> cable simplifies ATX power supply control connections. When using this cable, please open jumper JP8 in order to ensure correct operation.



ATX Power Supply and Control Using Crystalfontz WR-PWR-Y14 Cable

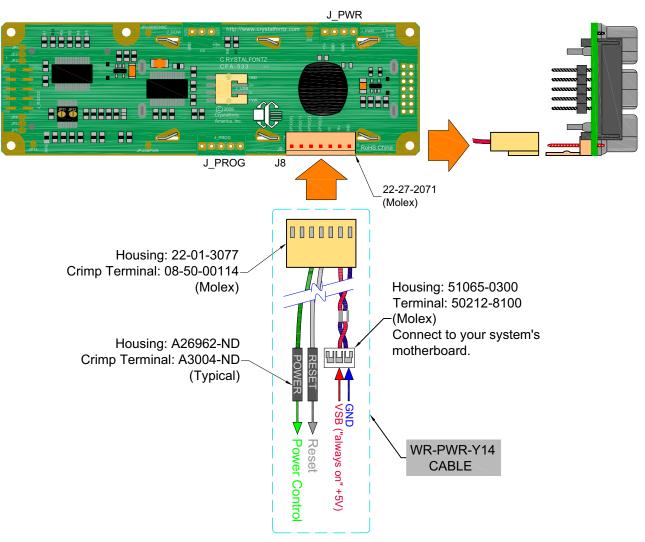


Figure 14. ATX Power Supply and Control Using Crystalfontz WR-PWR-Y14 Cable



<u>NOTE</u>

If the Crystalfontz <u>WR-PWR-Y14</u> cable is ordered at the same time as the LCD module, Crystalfontz will install the <u>WR-PWR-Y14</u> connector, open jumper JPUSBPWR, close JPUSBSENSE, and send the following software configuration commands (unless we are otherwise instructed). Please note that once these changes are made, if JP8 is not closed, power must be applied to +5v on the J_PWR connector and +5v on the J8 connector for the LCD module to power up. The module can not power up until the operating system allocates power to the LCD module, per the USB specification.

```
command = 28 // Set ATX Switch Functionality
length = 3
data[0] = 241 // Enable:
             // KEYPAD POWER OFF
             // KEYPAD POWER ON
             // KEYPAD RESET
                  LCD OFF IF HOST IS OFF
             11
             11
                  AUTO POLARITY
data[1] = 16 // One half second power pulses
             // sense ATX host power state on P0.7 (J PWR, +5v)
data[2] = 0
command = 4
             // Store current state as boot state
length = 0
```

ATX Keypad Control

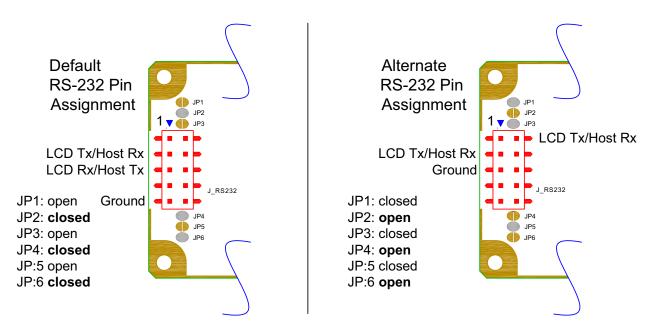
Once configured by the host software (see command <u>28 (0x1C): Set ATX Switch Functionality (Pg. 48)</u>), the following functions may be individually enabled:

- System power on. If POWER-ON SENSE is low (0th), pressing the green check key (Enter key) for 0.25 seconds will turn the unit on by driving POWER CONTROL line for the pulse width set by command <u>28 (0x1C)</u>: <u>Set ATX Switch Functionality (Pg. 48)</u> (1.0 seconds default).
- System hard power off. If POWER-ON SENSE is high (+5v power, V_{DD}) pressing the red X key (Cancel key) for 4 seconds will turn the system off by driving the POWER CONTROL line. The line will be driven for a minimum of the pulse width set by command <u>28 (0x1C)</u>: <u>Set ATX Switch Functionality (Pg. 48)</u> (1.0 seconds default). If the user continues to press the key, the CFA533-YYH-KU will continue to drive the line for up to an additional 5 seconds.
- System hard reset. If POWER-ON SENSE is high (+5v power, V_{DD}) pressing the green check key (Enter key) for 4 seconds will reset the system by driving the RESET line for 1 second. The CFA533-YYH-KU will reboot itself immediately after resetting the host.

Since the computer and LCD module must look off if the computer's power is off, the CFA533-YYH-KU can be configured to monitor the POWER-ON SENSE line and blank its display any time the POWER-ON SENSE line is low.



GPIO CONNECTIONS



The CFA533-YYH-KU has five General-Purpose Input/Output (GPIO) pins. The GPIO are port pins from the CFA533-YYH-KU's microcontroller brought out to connectors. As an output, a GPIO can be used to turn on an LED, or perhaps drive a relay. As an input, a GPIO can be used to read a switch or a button. Most of the GPIOs have a default function that allows the LCD module to perform some special purpose activity with the pin.

```
GPIO[0] = J8, Pin 7
GPIO[1] = J8, Pin 6 (may be used as ATX Host Power Sense, has R21 in series)
GPIO[2] = J8, Pin 5 (default is ATX Host Power Control)
GPIO[3] = J8, Pin 4 (default is ATX Host Reset Control)
GPIO[4] = J_DOW, Pin 2 (default is DOW I/O--may have 1 KΩ hardware pull-up: R7)
```

GPIO[0], GPIO[2] and GPIO[3] are connected directly from the microcontroller port pin to the connector pin.

GPIO[1] has a series $5k\Omega$ resistor in R21.

GPIO[4] is also used as the DOW I/O pin. Since the DOW requires a pull-up on the I/O pin, a $1k\Omega$ resistor in R7 is loaded to pull GPIO[4] to V_{DD} (+5v power).



Please refer to commands <u>34 (0x22): Set/Configure GPIO (Pg. 52)</u> and <u>35 (0x23): Read GPIO Pin Levels and</u> <u>Configuration State (Pg. 53)</u> for additional details concerning the GPIO operation.

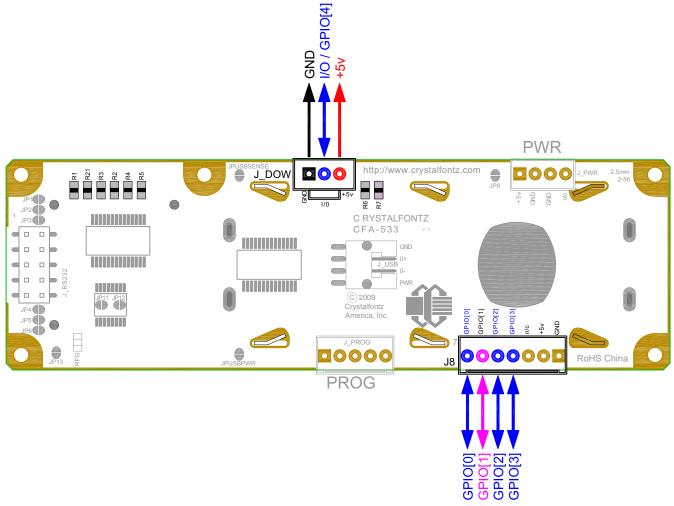


Figure 15. Location of GPIO Connections, Resistors, and J_DOW

DALLAS SEMICONDUCTOR 1-WIRE DEVICE CONNECTIONS FOR OPTIONAL ACCESSORIES

Temperature Sensors

The CFA533-YYH-KU supports Dallas Semiconductor 1-Wire (DOW) temperature sensors. See location of J_DOW in <u>Figure 15. on Pg. 32</u>. By default, J_DOW is not loaded with a connector. If you request it, Crystalfontz can load a Molex 70543-0002. For information, please contact technical support (+1-888-206-9720 or email <u>technifo@crystalfontz.com</u>). We will provide you with a semi-custom part number and pricing. A minimum order quantity may apply.

Any combination of up to 32 <u>DS1822</u> Econo 1-Wire Digital Thermometer (2°C absolute accuracy) or <u>DS18B20</u> High Precision 1-Wire Digital Thermometer (0.5°C absolute accuracy) temperature sensors or other DOW compatible devices are directly supported.



The Crystalfontz <u>WR-DOW-Y17</u> has a DS18B20 attached to a "daisy chain" cable. If a <u>WR-DOW-Y17</u> is ordered at the same time as a CFA533-YYH-KU, Crystalfontz can load the WR-DOW-Y17's mating connector into the CFA533-YYH-KU's DOW position. For reference, the mating connector for the <u>WR-DOW-Y17</u> is <u>Molex 70543-0002</u> available from Digi-Key or other parts suppliers.

The temperature sensor can be configured to be automatically read and displayed on the CFA533-YYH-KU's LCD in °C or °F (see command <u>21 (0x15)</u>: <u>Set Up Live Temperature Display (Pg. 45)</u>). Independently, any temperature sensor can be configured to report to the host (see <u>19 (0x13)</u>: <u>Set Up Temperature Reporting (Pg. 44)</u>). The sensors configured to be reported are updated once each second.

Other 1-Wire Devices

Other <u>Dallas Semiconductor 1-Wire devices</u> may be connected to the 1-Wire bus, with the CFA533-YYH-KU acting as a bridge between USB and the 1-Wire bus (see command <u>21 (0x15): Set Up Live Temperature Display (Pg. 45)</u>). The total number of 1-Wire devices supported is 32, including directly supported temperature sensors and any other user-provided 1-Wire devices. (See CFA533-YYH-KU's DOW connection location in <u>Figure 15</u>. on Pg. 32.) The LCD module can send up to 15 bytes and receive up to 14 bytes. This will be sufficient for many devices but some devices require larger transactions and cannot be fully used with the module.

The CFA533-YYH-KU has a $1k\Omega$ hardware pull-up on the DOW connector's I/O line.

Connect the 1-Wire sensors as detailed in the sensor's data sheet.

HOST COMMUNICATIONS

<u>NOTE</u>

Because there is no difference in communications and commands for I²C variants (part numbers ending in "-KC"), serial variants (part numbers ending in "-KL" or "-KS") and USB variants (part numbers ending in "-KU") of the CFA533, the Host Communications section of this Data Sheet uses the shorter term "CFA533" instead of "CFA533-YYH-KU".

The CFA533 series (includes CFA533-YYH-KU) communicates with its host using an RS-232 interface. The port settings are 19200 baud, 8 data bits, no parity, 1 stop bit by factory default. The speed can be set to 115200 baud under software control (see command <u>33 (0x21): Set Baud Rate (Pg. 51)</u>).

PACKET STRUCTURE

All communication between the CFA533 and the host takes place in the form of a simple and robust CRC checked packet. The packet format allows for very reliable communications between the CFA533 and the host without the



traditional problems that occur in a stream-based serial communication (such as having to send data in inefficient ASCII format, to "escape" certain "control characters", or losing sync if a character is corrupted, missing, or inserted).

<u>NOTE</u>

Reconciling packets is recommended rather than using delays when communicating with the LCD module. To reconcile your packets, please ensure that you have received the acknowledgement packet from the packet most recently sent before sending any additional packets to the LCD module. This practice will guarantee that you will not have any dropped packets or missed communication with the LCD module.

All packets have the following structure:

```
<type><data_length><data><CRC>
```

type is one byte, and identifies the type and function of the packet:

data_length specifies the number of bytes that will follow in the data field. The valid range of data_length is 0 to 18.

data is the payload of the packet. Each type of packet will have a specified data_length and format for data as well as algorithms for decoding data detailed below.

CRC is a standard 16-bit CRC of all the bytes in the packet except the CRC itself. The CRC is sent LSB first. At the port, the CRC immediately follows the last used element of data []. See <u>APPENDIX B: SAMPLE CODE</u> <u>AND CALCULATING THE CRC (Pg. 65)</u> for several examples of how to calculate the CRC in different programming languages.

The following concept may be useful for understanding the packet structure.

```
typedef struct
    {
    unsigned char
    command;
    unsigned char
    data_length;
    unsigned char
    data[data_length];
    unsigned short
    CRC;
    }COMMAND_PACKET;
```

Crystalfontz supplies a demonstration and test program <u>633WinTest</u> along with its C source code. Both will work with the CFA533 modules. Included in the <u>633WinTest</u> source is a CRC algorithm and an algorithm that detects packets. The algorithm will automatically re-synchronize to the next valid packet in the event of any communications errors. Please follow the algorithm in the sample code closely in order to realize the benefits of using the packet communications.



ABOUT HANDSHAKING

The nature of CFA533's packets makes it unnecessary to implement traditional hardware or software handshaking.

The host should wait for a corresponding acknowledge packet from the CFA533 before sending the next command packet. The CFA533 will respond to all packets within 250 mS. The host software should stop waiting and retry the packet if the CFA533 fails to respond within 250 mS. The host software should report an error if a packet is not acknowledged after several retries. This situation indicates a hardware problem — for example, a disconnected cable.

Please note that some operating systems may introduce delays between when the data arrives at the physical port from the CFA533 until it is available to the user program. In this case, the host program may have to increase its timeout window to account for the additional overhead of the operating system.

The CFA533 can be configured to send several types of report packets along with regular acknowledge packets. The host should be able to buffer several incoming packets and must guarantee that it can process and remove packets from its input buffer faster than the packets can arrive given the baud rate and the reporting configuration of the CFA533. For any modern PC using reasonably efficient software, this requirement will not pose a challenge.

The report packets are sent asynchronously with respect to the command packets received from the host. The host should not assume that the first packet received after it sends a command is the acknowledge packet for that command. The host should inspect the type field of incoming packets and process them accordingly.

REPORT CODES

The CFA533 can be configured to report two items. The CFA533 sends reports automatically when the data becomes available. Reports are not sent in response to a particular packet received from the host. The two report types are:

0x80: Key Activity

If a key is pressed or released, the CFA533 sends a Key Activity report packet to the host. Key event reporting may be individually enabled or disabled by command <u>23 (0x17): Configure Key Reporting (Pg. 46)</u>.

```
type: 0x80
data length: 1
data[0] is the type of keyboard activity:
       KEY UP PRESS
                                  1
       KEY DOWN PRESS
                                  2
       KEY LEFT PRESS
                                  3
       KEY RIGHT PRESS
                                  4
       KEY ENTER PRESS
                                  5
                                  6
       KEY EXIT PRESS
       KEY_UP_RELEASE
                                  7
       KEY DOWN RELEASE
                                  8
       KEY LEFT RELEASE
                                  9
       KEY RIGHT RELEASE
                                 10
       KEY ENTER RELEASE
                                 11
       KEY EXIT RELEASE
                                 12
```

These codes are identical to the codes returned by the <u>CFA633</u>, <u>CFA635</u>, and <u>XES635</u>. Please note that the <u>CFA631</u> will return codes 13 through 20. (See the <u>CFA631</u> Data Sheet on our website for more details).

0x81: (reserved)



0x82: Temperature Sensor Report

If any of the up to 32 temperature sensors is configured to report to the host, the CFA533 will send Temperature Sensor Reports for each selected sensor every second. See the command $\underline{19 (0x13)}$: Set Up Temperature Reporting (Pg. 44) below.

```
type: 0x82
data_length: 4
data[0] is the index of the temperature sensor being reported:
        0 = temperature sensor 1
        1 = temperature sensor 2
        . . .
        31 = temperature sensor 32
data[1] is the LSB of Temperature_Sensor_Counts
data[2] is the MSB of Temperature_Sensor_Counts
data[3] is DOW crc status
```

The following C function will decode the Temperature Sensor Report packet into °C and °F:

```
void OnReceivedTempReport(COMMAND PACKET *packet, char *output)
  //First check the DOW CRC return code from the CFA533
  if(packet->data[3]==0)
    strcpy(output,"BAD CRC");
  else
    double
      deac;
    degc=(*(short *)&(packet->data[1]))/16.0;
    double
      degf;
    degf = (degc*9.0)/5.0+32.0;
    sprintf(output, "%9.4f°C =%9.4f°F",
            degc,
            degf);
    }
  }
```

COMMAND CODES

Below is a list of valid commands for the CFA533. Each command packet is answered by either a response packet or an error packet. The low 6 bits of the type field of the response or error packet is the same as the low 6 bits of the type field of the command packet being acknowledged.

0 (0x00): Ping Command

The CFA533 will return the Ping Command to the host.

```
type: 0x00 = 0<sub>10</sub>
valid data_length is 0 to 16
data[0-(data_length-1)] can be filled with any arbitrary data
```

The return packet is identical to the packet sent, except the type will be 0x40 (normal response, Ping Command):

```
type: 0x40 | 0x00 = 0x40 = 64<sub>10</sub>
data_length: (identical to received packet)
data[0-(data length-1)] = (identical to received packet)
```

1 (0x01): Get Hardware & Firmware Version

The CFA533 will return the hardware and firmware version information to the host.



type: $0x01 = 1_{10}$ valid data length is 0

The return packet will be:

```
type: 0x40 | 0x01 = 0x41 = 65<sub>10</sub>
data_length: 16
data[] = "CFA533:hX.X,yY.Y"
hX.X is the hardware revision, "1.0" for example
yY.Y is the firmware version, "u1.0" for example
```

2 (0x02): Write User Flash Area

The CFA533 reserves 16 bytes of nonvolatile memory for arbitrary use by the host. This memory can be used to store data such as a serial number, IP address, gateway address, netmask, or any other data required. All 16 bytes must be supplied.

```
type: 0x02 = 2_{10}
valid data length is 16
data[] = 16 bytes of arbitrary user data to be stored in the CFA533's non-volatile memory
```

The return packet will be:

type: $0x40 | 0x02 = 0x42 = 66_{10}$ data_length: 0

3 (0x03): Read User Flash Area

This command will read the User Flash Area and return the data to the host.

type: 0x03 = 3₁₀
valid data_length is 0

The return packet will be:

```
type: 0x40 \mid 0x03 = 0x43 = 67_{10}
data_length: 16
data[] = 16 bytes user data recalled from the CFA533's non-volatile memory
```

4 (0x04): Store Current State as Boot State

ERRATA NOTE

At voltages lower than +5v, the operation of reading from the LCD to the microcontroller may not work correctly. If this happens, you will see corrupted characters on the LCD after using Command 4 and rebooting the module.

- One workaround is to supply +5v to the module during the Command 4 operation.
- Another workaround is to have Crystalfontz set the boot state for you at the factory, using a semicustom part number.

Please write <u>techinfo@crystalfontz.com</u> if you have questions regarding this errata.

The CFA533 loads its power-up configuration from nonvolatile memory when power is applied. The CFA533 is configured at the factory to display a welcome screen when power is applied. This command can be used to customize the welcome screen, as well as the following items:

• Characters shown on LCD, which are affected by:



- command <u>6 (0x06): Clear LCD Screen (Pg. 39)</u>.
- command <u>7 (0x07): Set LCD Contents, Line 1 (Pg. 39)</u>.
- command <u>8 (0x08): Set LCD Contents, Line 2 (Pg. 40)</u>.
- command <u>31 (0x1F): Send Data to LCD (Pg. 51)</u>.
- Special character font definitions (command <u>9 (0x09): Set LCD Special Character Data (Pg. 40)</u>).
- Cursor position (command <u>11 (0x0B): Set LCD Cursor Position (Pg. 41)</u>).
- Cursor style (command <u>12 (0x0C): Set LCD Cursor Style (Pg. 41)</u>).
- Contrast setting (command <u>13 (0x0D): Set LCD Contrast (Pg. 41)</u>).
- LCD backlight setting (command <u>14 (0x0E): Set LCD & Keypad Backlight (Pg. 42)</u>).
- Keypad backlight setting (command <u>14 (0x0E): Set LCD & Keypad Backlight (Pg. 42)</u>).
- Settings of any live displays (command 21 (0x15): Set Up Live Temperature Display (Pg. 45)).
- Key press and release masks (command <u>23 (0x17): Configure Key Reporting (Pg. 46)</u>).
- ATX function enable and pulse length settings (command <u>28 (0x1C): Set ATX Switch Functionality (Pg. 48)</u>).
- Baud rate (command <u>33 (0x21): Set Baud Rate (Pg. 51)</u>).
- GPIO settings (command <u>34 (0x22): Set/Configure GPIO (Pg. 52)</u>).

You cannot store the temperature reporting (although the live display of temperatures can be saved). You cannot store the host watchdog. The host software should enable this item once the system is initialized and it is ready to receive the data.

type: $0x04 = 4_{10}$ valid data_length is 0

The return packet will be:

type: $0x40 | 0x04 = 0x44 = 68_{10}$ data_length: 0

5 (0x05): Reboot CFA533, Reset Host, or Power Off Host

This command instructs the CFA533 to simulate a power-on restart of itself, reset the host, or turn the host's power off. The ability to reset the host may be useful to allow certain host operating system configuration changes to complete. The ability to turn the host's power off under software control may be useful in systems that do not have ACPI compatible BIOS.

<u>NOTE</u>

The GPIO pins used for ATX control must not be configured as user GPIO, and must be configured to their default drive mode in order for the ATX functions to work correctly. These settings are factory default, but may be changed by the user. Please see command <u>34 (0x22): Set/Configure</u> <u>GPIO (Pg. 52)</u>.

Rebooting the CFA533 may be useful when testing the boot configuration. It may also be useful to re-enumerate the devices on the 1-Wire bus. To reboot the CFA533, send the following packet:

```
type: 0x05 = 5_{10}
valid data_length is 3
data[0] = 8
data[1] = 18
data[2] = 99
```



To reset the host, assuming the host's reset line is connected to GPIO[3] as described in command <u>28 (0x1C): Set ATX</u> Switch Functionality (Pg. 48), send the following packet:

```
type: 0x05 = 5_{10}
valid data length is 3
data[0] = 12
data[1] = 28
data[2] = 97
```

To turn the host's power off, assuming the host's power control line is connected to GPIO[2] as described in command <u>28 (0x1C): Set ATX Switch Functionality (Pg. 48)</u>, send the following packet:

```
type: 0x05 = 5_{10}
valid data length is 3
data[0] = 3
data[1] = 11
data[2] = 95
```

In any of the above cases, the return packet will be:

```
type: 0x40 \mid 0x05 = 0x45 = 69_{10} data_length: 0
```

6 (0x06): Clear LCD Screen

Sets the contents of the LCD screen DDRAM to ' $= 0x20 = 32_{10}$ and moves the cursor to the left-most column of the top line.

```
type: 0x06 = 6_{10}
valid data length is 0
```

The return packet will be:

type: $0x40 \mid 0x06 = 0x46 = 70_{10}$ data_length: 0

Clear LCD Screen changes the LCD. The LCD contents is one of the items stored by the command <u>4 (0x04): Store</u> Current State as Boot State (Pg. 37).

7 (0x07): Set LCD Contents, Line 1

Sets the center 16 characters displayed for the top line of LCD screen.

NOTE

Please use this command only if you need backwards compatibility with older <u>CFA633</u> units. For new applications, please use the more flexible command <u>31 (0x1F): Send Data to LCD (Pg. 51)</u> which is also supported by the <u>CFA631</u> and <u>CFA635</u>.

```
type: 0x7 = 7<sub>10</sub>
valid data_length is 16
data[] = top line's display content (must supply 16 bytes)
```

The return packet will be:

```
type: 0x40 \mid 0x07 = 0x47 = 71_{10} data_length: 0
```

Set LCD Contents, Line 1 is one of the items stored by the command <u>4 (0x04): Store Current State as Boot</u> State (Pg. 37).



8 (0x08): Set LCD Contents, Line 2

Sets the center 16 characters displayed for the bottom line of LCD screen.

<u>NOTE</u>

Please use this command only if you need backwards compatibility with older <u>CFA633</u> units. For new applications, please use the more flexible command <u>31 (0x1F): Send Data to LCD (Pg. 51)</u> which is also supported by the CFA631 and CFA635.

```
type: 0x08 = 8<sub>10</sub>
valid data_length is 16
data[] = bottom line's display content (must supply 16 bytes)
```

The return packet will be:

type: $0x40 | 0x08 = 0x48 = 72_{10}$ data_length: 0

Set LCD Contents, Line 2 is one of the items stored by the command <u>4 (0x04): Store Current State as Boot</u> State (Pg. 37).

9 (0x09): Set LCD Special Character Data

Sets the font definition for one of the special characters (CGRAM).

```
type: 0x09 = 9_{10}
valid data_length is 9
data[0] = index of special character that you would like to modify, 0-7 are valid
data[1-8] = bitmap of the new font for this character
```

data [1-8] are the bitmap information for this character. Any value is valid between 0 and 63, the msb is at the left of the character cell of the row, and the lsb is at the right of the character cell. data [1] is at the top of the cell, data [8] is at the bottom of the cell.

The return packet will be:

type: $0x40 | 0x09 = 0x49 = 73_{10}$ data length: 0

Set LCD Special Character Data is one of the items stored by the command <u>4 (0x04): Store Current State as Boot</u> State (Pg. 37).

10 (0x0A): Read 8 Bytes of LCD Memory

This command will return the contents of the LCD's DDRAM or CGRAM. This command is intended for debugging.

```
type: 0x0A = 10<sub>10</sub>
valid data_length is 1
data[0] = address code of desired data
```

data[0] is the address code native to the LCD controller:

0x40 (\064) to 0x7F (\127) for CGRAM 0x80 (\128) to 0x93 (\147) for DDRAM, line 1 0xC0 (\192) to 0xD3 (\211) for DDRAM, line 2

The return packet will be:

type: $0x40 | 0x0A = 0x4A = 74_{10}$ data_length: 9



data [0] of the return packet will be the address code. data [1-8] of the return packet will be the data read from the LCD controller's memory.

11 (0x0B): Set LCD Cursor Position

This command allows the cursor to be placed at the desired location on the CFA533's LCD screen. If you want the cursor to be visible, you may also need to send a command <u>12 (0x0C): Set LCD Cursor Style (Pg. 41)</u>.

```
type: 0x0B = 11<sub>10</sub>
valid data_length is 2
data[0] = column (0-15 valid)
data[1] = row (0-1 valid)
```

The return packet will be:

type: $0x40 | 0x0B = 0x4B = 75_{10}$ data length: 0

Set LCD Cursor Position is one of the items stored by the command 4 (0x04): Store Current State as Boot State (Pg. 37).

12 (0x0C): Set LCD Cursor Style

This command allows you to select among four hardware generated cursor options.

```
type: 0x0C = 12<sub>10</sub>
valid data_length is 1
data[0]: cursor style (0-3 valid)
    0 = no cursor
    1 = blinking block cursor
    2 = underscore cursor
    3 = blinking underscore (Note: This behavior is not the same as the CFA633 series
    which is: blinking block plus underscore.
```

The return packet will be:

type: $0x40 | 0x0C = 0x4C = 76_{10}$ data_length: 0

Set LCD Cursor Style is one of the items stored by the command <u>4 (0x04): Store Current State as Boot</u> State (Pg. 37).

13 (0x0D): Set LCD Contrast

This command sets the contrast or vertical viewing angle of the display. (Initiated by the host, responded to by the CFA533.)

• <u>CFA633</u> Compatible

If only one byte of data is supplied, then it is the "<u>CFA633</u> Compatible" version of the command. Requires 1 byte (0-200) are valid, but only (0-50) are useful for this LCD.

The return packet will be:



type: $0x40 | 0x0D = 0x4D = 77_{10}$ data_length: 0

• CFA533 Enhanced

If two bytes of data are supplied, then the command takes advantage of the CFA533s native enhanced contrast resolution. Requires 2 bytes.

- The first byte data[0] is ignored, any value from 0 to 255 is accepted.
- The second byte data[1] controls the CFA533 contrast with better resolution.

```
type: 0x0D = 13<sub>10</sub>
valid data_length is 1
data[0]: required but ignored
data[1]: contrast setting (0-200 valid)
                  0-99 = lighter
                 100 = no correction
                 101-200 = darker
```

The return packet will be:

type: $0x40 | 0x0D = 0x4D = 77_{10}$ data_length: 0

Set LCD Contrast is one of the items stored by the command 4 (0x04): Store Current State as Boot State (Pg. 37).

14 (0x0E): Set LCD & Keypad Backlight

This command sets the brightness of the LCD and keypad backlights. (Initiated by the host, responded to by the CFA533.)

• If one byte is supplied, both the keypad and LCD backlights are set to that brightness (CFA633 compatible).

The return packet will be:

type: $0x40 | 0x0E = 0x4E = 78_{10}$ data_length: 0

 If two bytes are supplied, the LCD is set to the brightness of the first byte, the keypad is set to the brightness of the second byte.

```
type: 0x0E = 14<sub>10</sub>
valid data_length is 2
data[0]: LCD backlight power setting (0-100 valid)
            0 = off
    1-100 = variable brightness
data[1]: keypad backlight power setting (0-100 valid)
            0 = off
    1-100 = variable brightness
```

The return packet will be:

type: $0x40 | 0x0E = 0x4E = 78_{10}$ data length: 0



Set LCD & Keypad Backlight is one of the items stored by the command <u>4 (0x04): Store Current State as Boot</u> State (Pg. 37).

15-17 (0x0F-0x11): (reserved)

18 (0x12): Read DOW Device Information

When power is applied to the CFA533, it detects any devices connected to the Dallas Semiconductor 1-Wire (DOW) bus and stores the device's information. This command will allow the host to read the device's information.

The first byte returned is the "family code" of the Dallas 1-Wire / iButton device. There is a list of the possible Dallas 1-Wire / iButton device family codes available in <u>App Note 155: 1-Wire Software Resource Guide</u> on the Maxim/Dallas website.

NOTE ON COMMAND 18: READ DOW DEVICE INFORMATION

The GPIO pin used for DOW must not be configured as user GPIO. It must be configured to its default drive mode in order for the DOW functions to work correctly.

These settings are factory default but may be changed by the user. Please see command <u>34 (0x22):</u> <u>Set/Configure GPIO (Pg. 52)</u>.

In order for the DOW subsystem to be enabled and operate correctly, user GPIO[4] must be configured as:

DDD = "111: 1=Hi-Z, 0=Slow, Strong Drive Down". F = "0: Port unused for user GPIO."

This state is the factory default, but it can be changed and saved by the user. To ensure that GPIO[4] is set correctly and the DOW operation is enabled, send the following command:

```
command = 34
length = 3
data[0] = 4
data[1] = 100
data[2] = 7
```

This setting must be saved as the boot state, so when the CFA533 reboots it will detect the DOW devices.

```
type: 0x12 = 18<sub>10</sub>
valid data_length is 1
data[0] = device index (0-31 valid)
```

The return packet will be:

```
type: 0x40 | 0x12 = 0x52 = 82_{10}
data_length: 9
data[0] = device index (0-31 valid)
data[1-8] = ROM ID of the device
```

If data[1] is 0x22 (<u>DS1822</u> Econo 1-Wire Digital Thermometer temperature sensor) or 0x28 (<u>DS18B20</u> High Precision 1-Wire Digital Thermometer temperature sensor), then that device can be set up to automatically convert and report the temperature every second. See the command <u>19 (0x13): Set Up Temperature Reporting (Pg. 44)</u>.



19 (0x13): Set Up Temperature Reporting

This command will configure the CFA533 to report the temperature information to the host every second.

```
type: 0x13 = 19_{10}
valid data length is 4
data[0-3] = 32-bit bitmask indicating which temperature sensors are enabled to report
            (0-255 valid in each location)
data[0]
08 07 06 05
              04 03
                     02 01 Enable Reporting of sensor with
                             device index of:
                             0: 1 = enable, 0 = disable
                      _ _ _ _ _
                             1: 1 = enable, 0 = disable
                             2: 1 = enable, 0 = disable
                     -----
                  _ _ _ _ _ _ _ _ _ _
                             3: 1 = enable, 0 = disable
                             4: 1 = enable, 0 = disable
                 _ _ _ _ _ _ _ _ _ _ _
                         _ _ _
                             5: 1 = enable, 0 = disable
               _ _ _ _ _ _ _ _ _ _ _ _ _ _ _
                             6: 1 = enable, 0 = disable
                             7: 1 = enable, 0 = disable
    -----
data[1]
16 15 14 13
              12 11 10 09 Enable Reporting of sensor with
                             device index of:
                            8: 1 = enable, 0 = disable
                         - -
                             9: 1 = enable, 0 = disable
                      ----- 10: 1 = enable, 0 = disable
                      _ _ _ _ _ _
                            11: 1 = enable, 0 = disable
                      _ _ _ _ _
                            12: 1 = enable, 0 = disable
                    ----- 13: 1 = enable, 0 = disable
                    ----- 14: 1 = enable, 0 = disable
                   ----- 15: 1 = enable, 0 = disable
data[2]
              20 19 18 17 Enable Reporting of sensor with
24 23 22 21
                             device index of:
                         -- 16: 1 = enable, 0 = disable
                         --- 17: 1 = enable, 0 = disable
                      ----
                            18: 1 = enable, 0 = disable
                      ----- 19: 1 = enable, 0 = disable
                         --- 20: 1 = enable, 0 = disable
                      ----- 21: 1 = enable, 0 = disable
                   ----- 22: 1 = enable, 0 = disable
            ----- 23: 1 = enable, 0 = disable
data[3]
32 31 30 29
              28 27 26 25
                            Enable Reporting of sensor with
                             device index of:
                         -- 24: 1 = enable, 0 = disable
                          -- 25: 1 = enable, 0 = disable
                      ----- 26: 1 = enable, 0 = disable
                      _ _ _ _ _
                            27:
                                1 = enable, 0 = disable
                       ----- 28: 1 = enable, 0 = disable
                         --- 29: 1 = enable, 0 = disables
                    ----- 30: 1 = enable, 0 = disable
               ----- 31: 1 = enable, 0 = disable
```

Any sensor enabled must have been detected as a 0x22 (DS1822 temperature sensor) or 0x28 (DS18B20 temperature sensor) during DOW enumeration. This can be verified by using the command <u>18 (0x12): Read DOW Device</u> Information (Pg. 43).

The return packet will be:

type: $0x40 \mid 0x13 = 0x53 = 83_{10}$ data_length: 0



20 (0x14): Arbitrary DOW Transaction

The CFA533 can function as an RS-232 to Dallas 1-Wire bridge. The CFA533 can send up to 15 bytes and receive up to 14 bytes. This will be sufficient for many devices, but some devices require larger transactions and cannot be fully used with the CFA533.

This command allows you to specify arbitrary transactions on the 1-Wire bus. 1-Wire commands follow this basic layout:

<bus reset //Required
<address_phase> //Must be "Match ROM" or "Skip ROM"
<write_phase> //optional, but at least one of write_phase or read_phase must be sent
<read phase> //optional, but at least one of write phase or read_phase must be sent

Please see <u>APPENDIX C: CONNECTING A DS2450 1-WIRE QUAD A/D CONVERTER (Pg. 77)</u> for an example of using this command.

```
type: 0x14 = 20<sub>10</sub>
valid data_length is 2 to 16
    data[0] = device_index (0-32 valid)
    data[1] = number_of_bytes_to_read (0-14 valid)
data[2-15] = data_to_be_written[data_length-2]
```

If device_index is 32, then no address phase will be executed. If device_index is in the range of 0 to 31, and a 1-Wire device was detected for that device_index at power on, then the write cycle will be prefixed with a "Match ROM" command and the address information for that device.

If data_length is two, then no specific write phase will be executed (although address information may be written independently of data_length depending on the value of device_index).

If data_length is greater than two, then data_length-2 bytes of data_to_be_written will be written to the 1-Wire bus immediately after the address phase.

If number_of_bytes_to_read is zero, then no read phase will be executed. If number_of_bytes_to_read is not zero then number_of_bytes_to_read will be read from the bus and loaded into the response packet.

The return packet will be:

21 (0x15): Set Up Live Temperature Display

You can configure the CFA533 to automatically update a portion of the LCD with a live temperature reading. Once the display is configured using this command, the CFA533 will continue to display the live reading on the LCD without host intervention. The Set Up Live Temperature Display is one of the items stored by command 4 (0x04): Store Current State as Boot State (Pg. 37), so you can configure the CFA533 to immediately display system temperatures as soon as power is applied.

The live display is based on a concept of display slots. There are 4 slots, and each of the 4 slots may be enabled or disabled independently.

Any slot may be requested to display any data that is available. For instance, slot 0 could display temperature sensor 3 in °C, while slot 1 could simultaneously display temperature sensor 3 in °F.



Any slot may be positioned at any location on the LCD, as long as all the digits of that slot fall fully within the display area. It is legal to have the display area of one slot overlap the display area of another slot, but senseless. This situation should be avoided in order to have meaningful information displayed.

```
type: 0x15 = 21_{10}
valid data length is 7 or 2 (for turning a slot off)
data[0]: display slot (0-7)
data[1]: type of item to display in this slot
       0 = nothing (data length then must be 2)
       1 = (invalid)
       2 = temperature (data_length then must be 7)
data[2]: index of the sensor to display in this slot:
       0-31 are valid for temperatures (and the temperature device must be attached)
data[3]: number of digits
       for a temperature: 3 digits (-XX or XXX)
       for a temperature: 5 digits (-XX.X or XXX.X)
data[4]: display column
       0-13 valid for a 3-digit temperature
       0-11 valid for a 5-digit temperature
data[5]: display row (0-1 valid)
data[6]: temperature units(0 = deg C, 1 = deg F)
```

If a 1-Wire CRC error is detected, the temperature will be displayed as "ERR" or "ERROR".

The return packet will be:

type: $0x40 \mid 0x15 = 0x55 = 85_{10}$ data_length: 0

22 (0x16): Send Command Directly to the LCD Controller

The controller on the CFA533 is a Neotec <u>NT7070B</u> (HD44780 compatible). Generally you won't need low-level access to the LCD controller but some arcane functions of the <u>NT7070B</u> are not exposed by the CFA533's command set. This command allows you to access the CFA533's LCD controller directly. Note: It is possible to corrupt the CFA533 display using this command.

The return packet will be:

type: $0x40 \mid 0x16 = 0x56 = 86_{10}$ data_length: 0

23 (0x17): Configure Key Reporting

By default, the CFA533 reports any key event to the host. This command allows the key events to be enabled or disabled on an individual basis. The key events set to report are one of the items stored by the command 4 (0x04): Store Current State as Boot State (Pg. 37).



#define KP_UP 0x01 #define KP_ENTER 0x02 #define KP_CANCEL 0x04 #define KP_LEFT 0x08 #define KP_RIGHT 0x10 #define KP_DOWN 0x20 type: 0x17 = 23₁₀ data_length: 2 data[0]: press mask data[1]: release mask

The return packet will be:

type: $0x40 \mid 0x17 = 0x57 = 87_{10}$ data_length: 0

Configure Key Reporting is one of the items stored by the command 4 (0x04): Store Current State as Boot State (Pg. 37).

24 (0x18): Read Keypad, Polled Mode

In some situations, it may be convenient for the host to poll the CFA533 for key activity. This command allows the host to detect which keys are currently pressed, which keys have been pressed since the last poll, and which keys have been released since the last poll.

This command is independent of the key reporting masks set by command <u>23 (0x17): Configure Key Reporting (Pg. 46)</u>. All keys are always visible to this command. Typically both masks of command 23 would be set to "0" if the host is reading the keypad in polled mode.

#define KP_UP 0x01
#define KP_ENTER 0x02
#define KP_CANCEL 0x04
#define KP_LEFT 0x08
#define KP_RIGHT 0x10
#define KP_DOWN 0x20
type: 0x18 = 24₁₀
data_length: 0

The return packet will be:

type: 0x40 | 0x18 = 0x58 = 88₁₀ data_length: 3 data[0] = bit mask showing the keys currently pressed data[1] = bit mask showing the keys that have been pressed since the last poll data[2] = bit mask showing the keys that have been released since the last poll

25-27 (0x19-0x1B): (reserved)



28 (0x1C): Set ATX Switch Functionality

The combination of the CFA533 with the Crystalfontz <u>WR-PWR-Y14</u> cable can be used to replace the function of the power and reset switches in a standard ATX-compatible system. The ATX Power Switch Functionality is one of the items stored by the command <u>4 (0x04)</u>: <u>Store Current State as Boot State (Pg. 37)</u>.

```
NOTE ON COMMAND 28: SET ATX SWITCH FUNCTIONALITY
 The GPIO pins used for ATX control must not be configured as user GPIO. The pins must be con-
 figured to their default drive mode in order for the ATX functions to work correctly.
 These settings are factory default but may be changed by the user. Please see command <u>34</u>
 (0x22): Set/Configure GPIO (Pg. 52). These settings must be saved as the boot state.
 To ensure that GPIO[1] will operate correctly as ATX SENSE, user GPIO[1] must be configured
 as:
    DDD = "011: 1=Resistive Pull Up, 0=Fast, Strong Drive Down".
     F = "0: Port unused for user GPIO."
 This configuration can be assured by sending the following command:
     command = 34
     length = 3
     data[0] = 1
     data[1] = 0
     data[2] = 3
 To ensure that GPIO[2] will operate correctly as ATX POWER, user GPIO[2] must be configured
 as:
     DDD = "010: Hi-Z, use for input".
     F = "0: Port unused for user GPIO."
 This configuration can be assured by sending the following command:
     command = 34
     length = 3
     data[0] = 2
     data[1] = 0
     data[2] = 2
 To ensure that GPIO[3] will operate correctly as ATX RESET, user GPIO[3] must be configured as:
     DDD = "010: Hi-Z, use for input".
     F = "0: Port unused for user GPIO."
 This configuration can be assured by sending the following command:
       command = 34
       length = 3
       data[0] = 3
       data[1] = 0
       data[2] = 2
 These settings must be saved as the boot state.
```

The RESET (GPIO[3]) and POWER CONTROL (GPIO[2]) lines on the CFA533 are normally high-impedance. Electrically, they appear to be disconnected or floating. When the CFA533 asserts the RESET or POWER CONTROL lines, they are momentarily driven high or low (as determined by the AUTO_POLARITY, RESET_INVERT or POWER_INVERT bits, detailed below). To end the power or reset pulse, the CFA533 changes the lines back to highimpedance.



FOUR FUNCTIONS MAY BE ENABLED BY COMMAND 28

Function 1: KEYPAD_RESET

If POWER-ON SENSE (GPIO[1]) is high, holding the green check key for 4 seconds will pulse RESET (GPIO[3]) pin for 1 second. During the 1-second pulse, the CFA533 will show "RESET", and then the CFA533 will reset itself, showing its boot state as if it had just powered on. Once the pulse has finished, the CFA533 will not respond to any commands until after it has reset the host and itself.

Function 2: KEYPAD_POWER_ON

If POWER-ON SENSE (GPIO[1]) is low, pressing the green check key for 0.25 seconds will pulse POWER CONTROL (GPIO[2]) for the duration specified by in data[1] or the default of 1 second. During this time the CFA533 will show "POWER ON", then the CFA533 will reset itself.

Function 3: KEYPAD_POWER_OFF

If POWER-ON SENSE (GPIO[1]) is high, holding the red X key for 4 seconds will pulse POWER CONTROL (GPIO[2]) for the duration specified by in data[1] or the default of 1 second. If the user continues to hold the power key down, then the CFA533 will continue to drive the line for a maximum of 5 additional seconds. During this time the CFA533 will show "POWER OFF".

Function 4: LCD_OFF_IF_HOST_IS_OFF

If LCD_OFF_IF_HOST_IS_OFF is set, the CFA533 will blank its screen and turn off its backlight to simulate its power being off any time POWER-ON SENSE is low.

<u>NOTE</u>

By default there is an internal POWER-ON-SENSE connected to the +5v pin of J_PWR, selected by setting data[2] to 1. Alternatively, GPIO[1] may be configured to act as POWER-ON-SENSE through R21 of 5K, and specifying data[2] as 0. The CFA533 will still be active (since it is powered by V_{SB} , standby power which is always-on), monitoring the keypad for a power-on keystroke.Once POWER-ON SENSE goes high, the CFA533 will reboot as if power had just been applied to it.

```
#define AUTO POLARITY
                              0x01 //Automatically detects polarity for reset and
                                   //power (recommended)
#define RESET INVERT
                              0x02 //Reset pin drives high instead of low
#define POWER INVERT
                              0x04 //Power pin drives high instead of low
#define LCD OFF IF HOST IS OFF 0x10
#define KEYPAD RESET
                              0 \times 20
#define KEYPAD POWER ON
                              0x40
#define KEYPAD POWER OFF
                              0 \times 80
type: 0 \times 1C = 28_{10}
data length: 1, 2 or 3
data[0]: bit mask of enabled functions
data[1]: (optional) length of power on & off pulses in 1/32 second
      1 = 1/32 \text{ sec}
      2 = 1/16 sec
     16 = 1/2 \text{ sec}
    255 = 8 \text{ sec}
1: sense ATX host state on P0.7 (JPWR,+5v -- recommended configuration))
```



The return packet will be:

type: $0x40 | 0x1C = 0x5C = 92_{10}$ data_length: 0

29 (0x1D): Enable/Feed Host Watchdog Reset

Some high-availability systems use hardware watchdog timers to ensure that a software or hardware failure does not result in an extended system outage. Once the host system has booted, a system monitor program is started. The system monitor program would enable the watchdog timer on the CFA533. If the system monitor program fails to feed the CFA533's watchdog timer, the CFA533 will reset the host system.

<u>NOTE</u>

The GPIO pins used for ATX control must not be configured as user GPIO. They must be configured to their default drive mode in order for the ATX functions to work correctly. These settings are factory default, but may be changed by the user. Please see the note under command 28 (0x1C): Set ATX Switch Functionality (Pg. 48) or command 34 (0x22): Set/Configure GPIO (Pg. 52).

```
type: 0x1D = 29<sub>10</sub>
data_length: 1
data[0] = enable/timeout
```

If timeout is 0, the watchdog is disabled.

If timeout is 1-255, then this command must be issued again within timeout seconds to feed the watchdog and avoid a watchdog reset.

To turn the watchdog off once it has been enabled, simply set timeout to 0.

If the command is not re-issued within timeout seconds, then the CFA533 will reset the host (see command 28 for details). Since the watchdog is off by default when the CFA533 powers up, the CFA533 will not issue another host reset until the host has once again enabled the watchdog.

The return packet will be:

type: $0x40 | 0x1D = 0x5D = 93_{10}$ data_length: 0

30 (0x1E): Read Reporting/ATX/Watchdog (debug)

This command can be used to verify the current items configured to report to the host, as well as some other miscellaneous status information. Please note that the information returned by the CFA533 is not identical to the information returned by other modules.

```
type: 0x1E = 30
data_length: 0
```



The return packet will be:

```
type = 0x40 | 0x1E = 0x5E = 94_{10}
data length: 15
data[0] = 0 (reserved)
data[1] = temperatures 1-8 reporting status (as set by command 19)
data[2] = temperatures 9-15 reporting status (as set by command 19)
data[3] = temperatures 16-23 reporting status (as set by command 19)
data[4] = temperatures 24-32 reporting status (as set by command 19)
data[5] = key presses (as set by command 23)
data[6] = key releases (as set by command 23)
data[7] = ATX Power Switch Functionality (as set by command 28)
data[8] = current watchdog counter (as set by command 29)
data[9] = User Contrast Adjust (as set by command 13, data[1])
data[10] = Key backlight setting (as set by command 14, data[1])
data[11] = atx sense on floppy (as set by command 28)
data[12] = 0 (reserved)
data[13] = CFA633-style contrast setting (as set by command 13, data[0])
data[14] = LCD backlight setting (as set by command 14, data[0])
```

Please Note: Future firmware versions may return fewer or additional bytes.

31 (0x1F): Send Data to LCD

This command allows data to be placed at any position on the LCD.

```
type: 0x1F = 31_{10}
data length: 3 to 18
data[0]: col = x = 0 to 15
data[1]: row = y = 0 to 1
data[2-21]: text to place on the LCD, variable from 1 to 16 characters
```

The return packet will be:

type: $0x40 | 0x1F = 0x5F = 95_{10}$ data length: 0

Send Data to LCD is one of the items stored by the command 4 (0x04): Store Current State as Boot State (Pg. 37).

32 (0x20): Reserved for CFA631 Key Legends

33 (0x21): Set Baud Rate

This command will change the CFA533's baud rate. The CFA533 will send the acknowledge packet for this command and then change its baud rate to the new value. The host should send the baud rate command, wait for a positive acknowledge from the CFA533 at the old baud rate, and then switch itself to the new baud rate. The baud rate must be saved by the command 4 (0x04): Store Current State as Boot State (Pg. 37) if you want the CFA533 to power up at the new baud rate.

The factory default baud rate is 19200.



The return packet will be:

type: $0x40 | 0x21 = 0x61 = 97_{10}$ data_length: 0

34 (0x22): Set/Configure GPIO

The CFA533 has five pins for user-definable general-purpose input / output (GPIO). These pins are shared with the DOW and ATX functions. Be careful when you configure the GPIO if you want to use the ATX or DOW at the same time.

The architecture of the CFA533 allows great flexibility in the configuration of the GPIO pins. They can be set as input or output. They can output constant high or low signals or a variable duty cycle 100 Hz PWM signal. (PWM Pulse Width Modulation is a way to simulate intermediate levels by switching a level between full on and full off. PWM is typically used to control the brightness of LED backlights, relying on the natural averaging done by the human eye.)

In output mode using the PWM (and a suitable current limiting resistor), an LED may be turned on or off and even dimmed under host software control. With suitable external circuitry, the GPIOs can also be used to drive external logic or power transistors.

The CFA533 continuously polls the GPIOs as inputs at 32 Hz. The present level can be queried by the host software at a lower rate. The CFA533 also keeps track of whether there were rising or falling edges since the last host query (subject to the resolution of the 32 Hz sampling). This means that the host is not forced to poll quickly in order to detect short events. The algorithm used by the CFA533 to read the inputs is inherently "bounce-free".

The GPIOs also have "pull-up" and "pull-down" modes. These modes can be useful when using the GPIO as an input connected to a switch since no external pull-up or pull-down resistor is needed. For instance, the GPIO can be set to pull up. Then when a switch connected between the GPIO and ground is open, reading the GPIO will return a "1". When the switch is closed, the input will return a "0".

Pull-up/pull-down resistance values are approximately 5kΩ. Do not exceed current of 25 mA per GPIO.

GPIO[1] may be connected to the host's power in order to sense the host's power on/off state. There is a resistor R21 in series with GPIO[1] to limit the possibility of <u>latchup</u>. To use GPIO[1] as a general-purpose input/output, you may need to change R21 with a resistor suitable for your application. It is loaded with a 5k Ω resistor that is suitable for most applications.

NOTE ON SETTING AND CONFIGURING GPIO PINS

The GPIO pins may also be used for ATX control through header J8 and temperature sensing through the CFA533's DOW header. By factory default, the GPIO output setting, function, and drive mode are set correctly to enable operation of the ATX and DOW functions. The GPIO output setting, function, and drive mode must be set to the correct values in order for the ATX and DOW functions to work. Improper use of this command can disable the ATX and DOW functions. The <u>633WinTest</u> will work with this CFA533 module and may be used to easily check and reset the GPIO configuration to the default state so the ATX and DOW functions will work.

The GPIO configuration is one of the items stored by the command 4 (0x04): Store Current State as Boot State (Pg. 37).

```
type: 0x22 = 34_{10}
data length:
 2 bytes to change value only
 3 bytes to change value and configure function and drive mode
data[0]: index of GPIO to modify
      0 = GPIO[0] = J8, Pin 7
      1 = GPIO[1] = J8, Pin 6 (may be ATX Host Power Sense, as configured by
                       command 28, data[2])
      2 = GPIO[2] = J8, Pin 5 (default is ATX Host Power Control)
      3 = GPIO[3] = J8, Pin 4 (default is ATX Host Reset Control)
      4 = GPIO[4] = J9, Pin 2 (default is DOW I/O--may have 1k\Omega hardware pull-up)
   5-255 = reserved
 Please note: Future versions of this command on future hardware models may accept
             additional values for data[0], which would control the state of future
             additional GPIO pins
data[1]: Pin output state (actual behavior depends on drive mode):
      0 = Output set to low
   1-99 = Output duty cycle percentage (100 Hz nominal)
    100 = Output set to high
 101-255 = invalid
data[2]: Pin function select and drive mode (optional, 0-15 valid)
      FDDD
       |||-- DDD = Drive Mode (based on output state of 1 or 0)
             000: 1=Fast, Strong Drive Up, 0=Resistive Pull Down
             001: 1=Fast, Strong Drive Up, 0=Fast, Strong Drive Down
             010: Hi-Z, use for input
             011: 1=Resistive Pull Up,
                                         0=Fast, Strong Drive Down
             100: 1=Slow, Strong Drive Up, 0=Hi-Z
             101: 1=Slow, Strong Drive Up, 0=Slow, Strong Drive Down
             110: reserved, do not use
             111: 1=Hi-Z,
                                          0=Slow, Strong Drive Down
       ---- F = Function
             0: Port unused for GPIO. It will take on the default
                function such as ATX, DOW or unused. The user is
                responsible for setting the drive to the correct
                value in order for the default function to work
                correctly.
             1: Port used for GPIO under user control. The user is
                responsible for setting the drive to the correct
                value in order for the desired GPIO mode to work
                correctly.
       ----- reserved, must be 0
```

The return packet will be:

type: $0x40 | 0x22 = 0x62 = 98_{10}$ data_length: 0

35 (0x23): Read GPIO Pin Levels and Configuration State

Please see command <u>34 (0x22): Set/Configure GPIO (Pg. 52)</u> for details on the GPIO architecture.



type: $0x23 = 35_{10}$

Crystalfontz America, Inc. www.crystalfontz.com January 2011

```
data length: 1
data[0]: index of GPIO to query
      0 = GPIO[0] = J8, Pin 7
       1 = GPIO[1] = J8, Pin 6 (may be ATX Host Power Sense, as configured
                               by command 28, data[2])
       2 = GPIO[2] = J8, Pin 5 (default is ATX Host Power Control)
       3 = GPIO[3] = J8, Pin 4 (default is ATX Host Reset Control)
       4 = GPIO[4] = J9, Pin 2 (default is DOW I/O--may have a 1k\Omega hardware pull-up)
   5-255 = reserved
 Please note: Future versions of this command on future hardware models may accept
 additional values for data[0], which would return the status of future additional GPIO
 pins
returns:
  data[0]: index of GPIO read
  data[1]: Pin state & changes since last poll
         - RES
          |||-- S = state at the last reading
           --- F = at least one falling edge has
                   been detected since the last poll
           ---- R = at least one rising edge has
                   been detected since the last poll
          ---- reserved
      (This reading is the actual pin state, which may or may not agree with the pin
      setting, depending on drive mode and the load presented by external circuitry.
The pins are polled at approximately 32 Hz asynchronously with respect to this
       command.Transients that happen between polls will not be detected.)
  data[2]: Requested Pin level/PWM level
    0-100 = Output duty cycle percentage
      (This value is the requested PWM duty cycle. The actual pin may or may not be
       toggling in agreement with this value, depending on the drive mode and the load
      presented by external circuitry)
  data[3]: Pin function select and drive mode
      -- FDDD
          |||-- DDD = Drive Mode
                000: 1=Fast, Strong Drive Up, 0=Resistive Pull Down
                001: 1=Fast, Strong Drive Up, 0=Fast, Strong Drive Down
                010: Hi-Z, use for input
                011: 1=Resistive Pull Up,
                                              0=Fast, Strong Drive Down
                100: 1=Slow, Strong Drive Up, 0=Hi-Z
                101: 1=Slow, Strong Drive Up, 0=Slow, Strong Drive Down
                110: reserved
               111: 1=Hi-Z,
                                              0=Slow, Strong Drive Down
          ---- F = Function
               0: Port unused for GPIO. It will take on the default
                  function such as ATX, DOW or unused. The user is
                  responsible for setting the drive to the correct
                  value in order for the default function to work
                  correctly.
                1: Port used for GPIO under user control. The user is
                  responsible for setting the drive to the correct
                  value in order for the desired GPIO mode to work
                  correctly.
         ----- reserved, will return 0
```



CHARACTER GENERATOR ROM (CGROM)

To find the code for a given character, add the two numbers that are shown in bold for its row and column. For example, the Greek letter " β " is in the column labeled "224d" and in the row labeled "2d". So 224 + 2 = 226. When you send a byte with the value of 226 to the display, the Greek letter " β " will be shown.

upper 4 bits	0 d	16 ₄	32 ₀	48 d	64 d	80 d	96 d	112 d	128d	144d	160 ₀	176 ₀	192 d	208 d	224 d	240 d
lower 4 bits	00002	00012	00102	0011,	0100 2	0101 ₂	0110	0111 ₂	10002	1001	10102	1011 ₂	11002	1101 ²	1110 ²	1111,
0d 00002	cgram															
1d 0001₂	cgram															
2d 0010₂	CGRAM															
3d 0011₂	^{cgram} [3]															
4 _d 0100₂	cgram [4]															
5d 0101₂	cgram [5]															
6d 0110₂	cgram [6]															
7a 0111₂	cgram [7]															
8d 1000₂	cgram [0]															
9₀ 1001₂	cgram															
10d 1010₂	^{cgram}															
11 _d 1011₂	^{cgram}															
12d 1100₂	cgram [4]															
13d 1101₂	^{CGRAM}															
14d 1110₂	^{cgram}															
15₀ 1111₂	cgram [7]															

Figure 16. Character Generator ROM (CGROM)



LCD MODULE RELIABILITY AND LONGEVITY

MODULE RELIABILITY

ITEM	SPECIFICATION
LCD portion (excluding Keypad and Backlights)	50,000 to 100,000 hours (typical)
Keypad	1,000,000 keystrokes
LED Backlights	50,000 to 100,000 hours (typical)

MODULE LONGEVITY (EOL / REPLACEMENT POLICY)

Crystalfontz is committed to making all of our LCD modules available for as long as possible. For each module we introduce, we intend to offer it indefinitely. We do not preplan a module's obsolescence. The majority of modules we have introduced are still available.

We recognize that discontinuing a module may cause problems for some customers. However, rapidly changing technologies, component availability, or low customer order levels may force us to discontinue ("End of Life", EOL) a module. For example, we must occasionally discontinue a module when a supplier discontinues a component or a manufacturing process becomes obsolete. When we discontinue a module, we will do our best to find an acceptable replacement module with the same fit, form, and function.

In most situations, you will not notice a difference when comparing a "fit, form, and function" replacement module to the discontinued module it replaces. However, sometimes a change in component or process for the replacement module results in a slight variation, perhaps an improvement, over the previous design.

Although the replacement module is still within the stated Data Sheet specifications and tolerances of the discontinued module, changes may require modification to your circuit and/or firmware. Possible changes include:

- *Backlight LEDs.* Brightness may be affected (perhaps the new LEDs have better efficiency) or the current they draw may change (new LEDs may have a different VF).
- Controller. A new controller may require minor changes in your code.
- *Component tolerances.* Module components have manufacturing tolerances. In extreme cases, the tolerance stack can change the visual or operating characteristics.

Please understand that we avoid changing a module whenever possible; we only discontinue a module if we have no other option. We will post Part Change Notices (PCN) on the product's webpage as soon as possible. If interested, you can subscribe to future part change notifications.



CARE AND HANDLING PRECAUTIONS

For optimum operation of the CFA533-YYH-KU and to prolong its life, please follow the precautions described below.

ELECTROSTATIC DISCHARGE (ESD)

The circuitry is industry standard CMOS logic and susceptible to ESD damage. Please use industry standard antistatic precautions as you would for any other static sensitive devices such as expansion cards, motherboards, or integrated circuits. Ground your body, work surfaces, and equipment.

DESIGN AND MOUNTING

- The exposed surface of the LCD "glass" is actually a polarizer laminated on top of the glass. To protect the soft plastic polarizer from damage, the module ships with a protective film over the polarizer. Please peel off the protective film slowly. Peeling off the protective film abruptly may generate static electricity.
- The polarizer is made out of soft plastic and is easily scratched or damaged. When handling the LCD module, avoid touching the polarizer. Finger oils are difficult to remove.
- CFA533-YYH-KU *without Crystalfontz overlay:* To protect the soft plastic polarizer from damage, place a transparent plate (for example, acrylic, polycarbonate, or glass) in front of the LCD module, leaving a small gap between the plate and the display surface. We use GE HP-92 Lexan, which is readily available and works well.
- Do not disassemble or modify the LCD module.
- Do not modify the six tabs of the metal bezel or make connections to them.
- Solder only to the I/O terminals. Use care when removing solder. It is possible to damage the PCB.
- Do not reverse polarity to the power supply connections. Reversing polarity will immediately ruin the LCD module.

AVOID SHOCK, IMPACT, TORQUE, OR TENSION

- Do not expose the LCD module to strong mechanical shock, impact, torque, or tension.
- Do not drop, toss, bend, or twist the LCD module.
- Do not place weight or pressure on the LCD module.

IF LCD PANEL BREAKS

- If the LCD panel breaks, be careful to not get the liquid crystal fluid in your mouth or eyes.
- If the liquid crystal fluid touches your skin, clothes, or work surface, wash it off immediately using soap and plenty of water.

CLEANING

- The polarizer (laminated to the glass) is soft plastic. The soft plastic is easily scratched or damaged. Be very careful when you clean the polarizer.
- Do not clean the polarizer with liquids. Do not wipe the polarizer with any type of cloth or swab (for example, Q-tips).
- Use the removable protective film to remove smudges (for example, fingerprints) and any foreign matter. If you no longer have the protective film, use standard transparent office tape (for example, Scotch® brand "Crystal Clear Tape"). If the polarizer is dusty, you may carefully blow it off with clean, dry, oil-free compressed air.



• CFA533-YYH-KU *without Crystalfontz overlay:* The exposed surface of the LCD "glass" is actually the front polarizer laminated to the glass. The polarizer is made out of a fairly soft plastic and is easily scratched or damaged. The polarizer will eventually become hazy if you do not take great care when cleaning it. Long contact with moisture (from condensation or cleaning) may permanently spot or stain the polarizer.

OPERATION

- Your circuit should be designed to protect the CFA533-YYH-KU from ESD and power supply transients.
- Observe the operating temperature limitations: a minimum of 0°C to a maximum of 50°C with minimal fluctuation. Operation outside of these limits may shorten life and/or harm display.
 - At lower temperatures of this range, response time is delayed.
 - At higher temperatures of this range, display becomes dark. (You may need to adjust the contrast.)
- Operate away from dust, moisture, and direct sunlight.

STORAGE AND RECYCLING

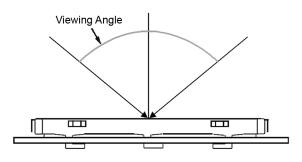
- Store in an ESD-approved container away from dust, moisture, and direct sunlight.
- Observe the storage temperature limitations: -10°C minimum, 60°C maximum with minimal fluctuation. Rapid temperature changes can cause moisture to form, resulting in permanent damage.
- Do not allow weight to be placed on the CFA533-YYH-KUs while they are in storage.
- Please recycle your outdated Crystalfontz modules at an approved facility.



APPENDIX A: QUALITY ASSURANCE STANDARDS

INSPECTION CONDITIONS

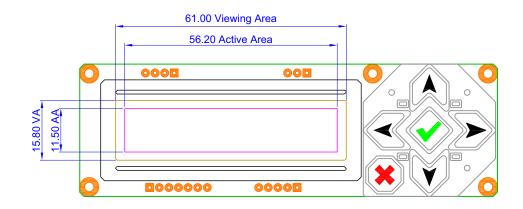
- Environment
 - Temperature: 25±5°C
 - Humidity: 30~85% RH
- For visual inspection of active display area
 - Source lighting: two 20 Watt or one 40 Watt fluorescent light
 - Display adjusted for best contrast
 - Viewing distance: 30±5 cm (about 12 inches)
 - Viewable angle: inspect at 45° angle of vertical line right and left, top and bottom



COLOR DEFINITIONS

We try to describe the appearance of our modules as accurately as possible. For the photos, we adjust for optimal appearance. Actual display appearance may vary due to (1) different operating conditions, (2) small variations of component tolerances, (3) inaccuracies of our camera, (4) color interpretation of the photos on your monitor, and/or (5) personal differences in the perception of color.

DEFINITION OF ACTIVE AREA AND VIEWABLE AREA





ACCEPTANCE SAMPLING

DEFECT TYPE	AQL*
Major	<u><</u> 0.65%
Minor	<u><</u> 1.00%
*Acceptable Quality Level: maximum allowable error r	ate or variation from standard

DEFECTS CLASSIFICATION

Defects are defined as:

- Major Defect: results in failure or substantially reduces usability of unit for its intended purpose
- Minor Defect: deviates from standards but is not likely to reduce usability for its intended purpose

ACCEPTANCE STANDARDS

#	DEFECT TYPE		CRITERIA					
1	Electrical defects		 No display, display malfunctions, or shorted segments. Current consumption exceeds specifications. 					
2	Viewing area defect	Viewing area does not r <u>Conditions (Pg. 59)</u> .	iewing area does not meet specifications. (See <u>Inspection</u> conditions (Pg. 59).					
3	Contrast adjustment defect	Contrast adjustment fails or malfunctions.						
4	4 Blemishes or foreign matter on display seg- ments Blemish		Defect Size (mm)	Acceptable Qty				
		Blemish	<u><</u> 0.3	3				
			<2 defects within 1	0 mm of each other	– Minor			
5	Other blemishes or for-	Defect size = (A + B)/2	Defect Size (mm)	Acceptable Qty				
	eign matter outside of display segments		<u><</u> 0.15	Ignore				
		Length Width	0.15 to 0.20	3	Minor			
			0.20 to 0.25	2				
			0.25 to 0.30	1				



#	DEFECT TYPE		CRITERIA		MAJOR / MINOR
6	Dark lines or scratches	Defect Width (mm)	Defect Length (mm)	Acceptable Qty	
	in display area	<u><</u> 0.03	<u><</u> 3.0	3	
	Nidt	0.03 to 0.05	<u><</u> 2.0	2	Minor
	Length	0.05 to 0.08	<u><</u> 2.0	1	Minor
		0.08 to 0.10	≤3.0	0	
		<u>></u> 0.10	>3.0	0	
7	Bubbles between polarize	r film and glass	Defect Size (mm)	Acceptable Qty	
			<u><</u> 0.20	Ignore	
			0.20 to 0.40	3	Minor
			0.40 to 0.60	2	
			<u>></u> 0.60	0	
8	Glass rest defect			′idth nickness - -	Minor
9	Display pattern defect	Dot Size (mm) ((A+B)/2)≤0.2 C>0 ((D+E)/2)≤0.25	≤3 total	able Qty defects es per digit	Minor
		((F+G)/2) <u><</u> 0.25	-		



#	DEFECT TYPE		CRI	TERIA		MAJOR / MINOR		
10	Chip in corner		a b c Acceptable Qty					
		а	b	С	Acceptable Qty			
		<4 mm	<u><</u> W	c <u>≺</u> T	3			
11	Chip on "non-contact" edge of LCD		b t t t t t t t t t t t t t t t t t t t	С		Minor		
			а	b	с			
			<u><</u> 3 mm	<u><</u> 1 mm	<u><</u> T			
			<u><</u> 4 mm	<u><</u> 1.5 mm	≤T			
12	Chip on "contact" edge of LCD, on the active side			W		Minor		
		а	b	с	Acceptable Qty			
		<u><</u> 2 mm	<u><</u> W/4	<u><</u> T	Ignore			
		<u><</u> 3 mm	<u><</u> W/4	<u><</u> T	3			



#	DEFECT TYPE		CRI	TERIA		MAJOR / MINOR		
13	Chip on "contact" edge of LCD, on the inactive side		W	b		Minor		
		а	b	С	Acceptable Qty			
		<u><</u> 3 mm	<u><</u> 1 mm	<u><</u> T	Ignore			
		<u><</u> 4 mm	<u><</u> 1.5 mm	<u><</u> T	3			
	Chip in seal area		display area www.a = length b = width c = thickness					
		а	b	С	Acceptable Qty			
		<3 mm	<u><</u> 1.5 mm	<u><</u> 1/2 T	3	Minor		
		Unacceptable if	c>50% of glass thic	kness or if the sea	al area is damaged.	Major		
15	Backlight defects	 Light fails or flickers.* Color and luminance do not correspond to specifications.* Exceeds standards for display's blemishes or foreign matter (see test <u>5, Pg. 60</u>), and dark lines or scratches (see test <u>6, Pg. 61</u>). *Minor if display functions correctly. Major if the display fails. 				Minor		
16	COB defects	2. Seal surface	 Pinholes >0.2 mm. Seal surface has pinholes through to the IC. More than 3 locations of sealant beyond 2 mm of the sealed areas. 					
17	PCB defects	 Wrong parts, Jumpers set i Solder (if any not smooth. 	contamination on co missing parts, or pa incorrectly.) on bezel, LED pa <i>lay functions correc</i>	arts not in specific d, zebra pad, or so	crew hole pad is	Minor		



#	DEFECT TYPE	CRITERIA	MAJOR / MINOR
18	Soldering defects	 Unmelted solder paste. Cold solder joints, missing solder connections, or oxidation.* Solder bridges causing short circuits.* Residue or solder balls. Solder flux is black or brown. *Minor if display functions correctly. Major if the display fails. 	Minor



APPENDIX B: SAMPLE CODE AND CALCULATING THE CRC

SAMPLE CODE

We encourage you to use the free sample code listed below. Please leave the original copyrights in the code.

- Windows compatible test/demonstration program and source. Supports CFA533 and CFA633. http://www.crystalfontz.com/product/633WinTest.html
- □ Linux compatible command-line demonstration program with C source code. Supports CFA533, CFA631, CFA632, CFA633, CFA634, and CFA635.

http://www.crystalfontz.com/product/linux_cli_examples.html

□ Supported by CrystalControl freeware.

http://www.crystalfontz.com/product/CrystalControl2.html

In addition, see <u>http://lcdproc.org/hardware.php3</u> for Linux LCD drivers. LCDproc is an open source project that supports many of the Crystalfontz displays.

ALGORITHMS TO CALCULATE THE CRC

Below are eight sample algorithms that will calculate the CRC of a CFA533 packet. Some of the algorithms were contributed by forum members and originally written for the <u>CFA631</u> and <u>CFA635</u>. The CRC used in the CFA533 is the same one that is used in IrDA, which came from PPP, which to at least some extent seems to be related to a CCITT (ref: Network Working Group Request for Comments: 1171) standard. At that point, the trail was getting a bit cold and diverged into several referenced articles and papers, dating back to 1983.

The polynomial used is $X^{16} + X^{12} + X^5 + X^0$ (0x8408) The result is bit-wise inverted before being returned.

Algorithm 1: "C" Table Implementation

This algorithm is typically used on the host computer, where code space is not an issue.

```
//This code is from the IRDA LAP documentation, which appears to
//have been copied from PPP:
11
// http://irda.affiniscape.com/associations/2494/files/Specifications/
IrLAP11 Plus Errata.zip
//I doubt that there are any worries about the legality of this code,
//searching for the first line of the table below, it appears that
//the code is already included in the linux 2.6 kernel "Driver for
//ST5481 USB ISDN modem". This is an "industry standard" algorithm
//and I do not think there are ANY issues with it at all.
typedef unsigned char ubyte;
typedef unsigned short word;
word get crc(ubyte *bufptr,word len)
  //CRC lookup table to avoid bit-shifting loops.
  static const word crcLookupTable[256] =
    {0x00000,0x01189,0x02312,0x0329B,0x04624,0x057AD,0x06536,0x074BF,
     0x08C48,0x09DC1,0x0AF5A,0x0BED3,0x0CA6C,0x0DBE5,0x0E97E,0x0F8F7,
     0x01081,0x00108,0x03393,0x0221A,0x056A5,0x0472C,0x075B7,0x0643E,
     0x09CC9,0x08D40,0x0BFDB,0x0AE52,0x0DAED,0x0CB64,0x0F9FF,0x0E876,
     0x02102, 0x0308B, 0x00210, 0x01399, 0x06726, 0x076AF, 0x04434, 0x055BD,
     0x0AD4A,0x0BCC3,0x08E58,0x09FD1,0x0EB6E,0x0FAE7,0x0C87C,0x0D9F5,
     0x03183,0x0200A,0x01291,0x00318,0x077A7,0x0662E,0x054B5,0x0453C,
```

```
0x0BDCB,0x0AC42,0x09ED9,0x08F50,0x0FBEF,0x0EA66,0x0D8FD,0x0C974,
      0x04204,0x0538D,0x06116,0x0709F,0x00420,0x015A9,0x02732,0x036BB,
      0x0CE4C,0x0DFC5,0x0ED5E,0x0FCD7,0x08868,0x099E1,0x0AB7A,0x0BAF3,
      0x05285,0x0430C,0x07197,0x0601E,0x014A1,0x00528,0x037B3,0x0263A,
      0x0DECD, 0x0CF44, 0x0FDDF, 0x0EC56, 0x098E9, 0x08960, 0x0BBFB, 0x0AA72,
      0x06306,0x0728F,0x04014,0x0519D,0x02522,0x034AB,0x00630,0x017B9,
      0x0EF4E, 0x0FEC7, 0x0CC5C, 0x0DDD5, 0x0A96A, 0x0B8E3, 0x08A78, 0x09BF1,
      0x07387,0x0620E,0x05095,0x0411C,0x035A3,0x0242A,0x016B1,0x00738,
      \texttt{0x0FFCF, 0x0EE46, 0x0DCDD, 0x0CD54, 0x0B9EB, 0x0A862, 0x09AF9, 0x08B70, 0x08B70,
      0x08408,0x09581,0x0A71A,0x0B693,0x0C22C,0x0D3A5,0x0E13E,0x0F0B7,
      0x00840,0x019C9,0x02B52,0x03ADB,0x04E64,0x05FED,0x06D76,0x07CFF,
      0x09489,0x08500,0x0B79B,0x0A612,0x0D2AD,0x0C324,0x0F1BF,0x0E036,
      0x018C1,0x00948,0x03BD3,0x02A5A,0x05EE5,0x04F6C,0x07DF7,0x06C7E,
      0x0A50A,0x0B483,0x08618,0x09791,0x0E32E,0x0F2A7,0x0C03C,0x0D1B5,
      0x02942,0x038CB,0x00A50,0x01BD9,0x06F66,0x07EEF,0x04C74,0x05DFD,
      0x0B58B,0x0A402,0x09699,0x08710,0x0F3AF,0x0E226,0x0D0BD,0x0C134,
      0x039C3,0x0284A,0x01AD1,0x00B58,0x07FE7,0x06E6E,0x05CF5,0x04D7C,
      0x0C60C,0x0D785,0x0E51E,0x0F497,0x08028,0x091A1,0x0A33A,0x0B2B3,
      0x04A44,0x05BCD,0x06956,0x078DF,0x00C60,0x01DE9,0x02F72,0x03EFB,
      0x0D68D,0x0C704,0x0F59F,0x0E416,0x090A9,0x08120,0x0B3BB,0x0A232,
      0x05AC5,0x04B4C,0x079D7,0x0685E,0x01CE1,0x00D68,0x03FF3,0x02E7A,
      0x0E70E,0x0F687,0x0C41C,0x0D595,0x0A12A,0x0B0A3,0x08238,0x093B1,
      0x06B46,0x07ACF,0x04854,0x059DD,0x02D62,0x03CEB,0x00E70,0x01FF9,
      0x0F78F, 0x0E606, 0x0D49D, 0x0C514, 0x0B1AB, 0x0A022, 0x092B9, 0x08330,
      0x07BC7,0x06A4E,0x058D5,0x0495C,0x03DE3,0x02C6A,0x01EF1,0x00F78};
register word
    newCrc;
newCrc=0xFFFF;
//This algorithm is based on the IrDA LAP example.
while(len--)
   newCrc = (newCrc >> 8) ^ crcLookupTable[(newCrc ^ *bufptr++) & 0xff];
//Make this crc match the one's complement that is sent in the packet.
return(~newCrc);
```

Algorithm 2: "C" Bit Shift Implementation

This algorithm was mainly written to avoid any possible legal issues about the source of the routine (at the request of the LCDproc group). This routine was "clean" coded from the definition of the CRC. It is ostensibly smaller than the table driven approach but will take longer to execute. This routine is offered under the GPL.

```
typedef unsigned char ubyte;
typedef unsigned short word;
word get crc(ubyte *bufptr,word len)
  register unsigned int
    newCRC;
  //Put the current byte in here.
  ubvte
    data;
  int
   bit count;
  //This seed makes the output of this shift based algorithm match
  //the table based algorithm. The center 16 bits of the 32-bit
  //"newCRC" are used for the CRC. The MSb of the lower byte is used
  //to see what bit was shifted out of the center 16 bit CRC
  //accumulator ("carry flag analog");
  newCRC=0x00F32100;
  while(len--)
    //Get the next byte in the stream.
    data=*bufptr++;
    //Push this byte's bits through a software
    //implementation of a hardware shift & xor.
```



```
for(bit count=0;bit count<=7;bit count++)</pre>
    //Shift the CRC accumulator
    newCRC>>=1;
    //The new MSB of the CRC accumulator comes
    //from the LSB of the current data byte.
    if(data&0x01)
      newCRC = 0x00800000;
    //If the low bit of the current CRC accumulator was set
    //before the shift, then we need to XOR the accumulator
    //with the polynomial (center 16 bits of 0x00840800)
    if(newCRC&0x0000080)
      newCRC<sup>^</sup>=0x00840800;
    //Shift the data byte to put the next bit of the stream
    //into position 0.
    data>>=1;
    }
  }
//All the data has been done. Do 16 more bits of 0 data.
for(bit_count=0;bit_count<=15;bit_count++)</pre>
  //Shift the CRC accumulator
 newCRC>>=1;
  //If the low bit of the current CRC accumulator was set
  //before the shift we need to XOR the accumulator with
  //0x00840800.
  if(newCRC&0x0000080)
   newCRC<sup>^</sup>=0x00840800;
//Return the center 16 bits, making this CRC match the one's
//complement that is sent in the packet.
return((~newCRC)>>8);
}
```

Algorithm 2B: "C" Improved Bit Shift Implementation

This is simplified algorithm that implements the CRC.



```
unsigned short get crc(unsigned char count, unsigned char *ptr)
  Ł
  unsigned short
           //Calculated CRC
    crc;
  unsigned char
    i;
          //Loop count, bits in byte
  unsigned char
    data; //Current byte being shifted
  crc = 0xFFFF; // Preset to all 1's, prevent loss of leading zeros
  while(count--)
    {
    data = *ptr++;
    i = 8;
    do
      {
      if((crc ^ data) & 0x01)
        {
        crc >>= 1;
        crc ^{=} 0x8408;
        }
      else
        crc >>= 1;
      data >>= 1;
      } while(--i != 0);
    }
  return (~crc);
  }
```

Algorithm 3: "PIC Assembly" Bit Shift Implementation

This routine was graciously donated by one of our customers.

```
; Crystalfontz CFA533 PIC CRC Calculation Example
; This example calculates the CRC for the hard coded example provided
; in the documentation.
; It uses "This is a test. " as input and calculates the proper CRC
; of 0x93FA.
#include "p16f877.inc"
; CRC16 equates and storage
;------
accuml
        equ
               40h
                      ; BYTE - CRC result register high byte
               41h
                       ; BYTE - CRC result register high low byte
accumh
        equ
                       ; BYTE - data register for shift
datareg
               42h
        equ
                       ; BYTE - bit counter for CRC 16 routine
; BYTE - storage for string memory read
         equ
               43h
               44h
Zero
        equ
               45h
                       ; BYTE - index for string memory read
index
        equ
                       ; BYTE - temp storage for CRC routine
              46h
savchr
        equ
               021h
seedlo
         equ
                       ; initial seed for CRC reg lo byte
seedhi
               0F3h
                       ; initial seed for CRC reg hi byte
         equ
```

; polyL polyH	equ equ	008h 084h	; ;	polynomial low byte polynomial high byte
-			==:	
	Test Progr			
;				
	org	0	;	reset vector = 0000H
;	clrf	PCLATH		ensure upper bits of PC are cleared
	clrf	STATUS		ensure page bits are cleared
	goto	main		jump to start of program
	goto	main	,	Jump to start of program
; ; ISR V	Vector			
; 15K (ector			
,	org	4		start of ISR
	goto	\$		jump to ISR when coded
;	9000	*	'	Jump to Ibk when touted
,	org	20	:	start of main program
main	019	20	'	Sourd of main program
	movlw	seedhi	;	setup intial CRC seed value.
	movwf	accumh		This must be done prior to
	movlw	seedlo		sending string to CRC routine.
	movwf	accuml	;	
	clrf	index	;	clear string read variables
;			'	
, main1				
	movlw	HIGH InputS	tr	; point to LCD test string
	movwf	PCLATH		latch into PCL,
	movfw	index	-	get index
	call	InputStr		get character
	movwf	Zero		setup for terminator test
	movf			see if terminator
	btfsc	STATUS, Z		skip if not terminator
	goto	main2		else terminator reached, jump out of loop
	call	CRC16		calculate new crc
	call			
	incf	index, f	;	send data to LCD
	goto	main1		bump index loop
	goto	maini	,	1005
; main2				
maina	movlw	00h		shift accumulator 16 more bits.
	call	CRC16	-	This must be done after sending
	movlw	00h		string to CRC routine.
	call	CRC16	;	string to the routine.
	Call	CKCIU	'	
;	comf	accumh, f		invert result
	-		-	Invert resurt
	comi	accuml,f	;	
;	movfw	accuml		get CPC low byte
	call			get CRC low byte
			-	send to LCD
	movfw	accumh		get CRC hi byte
_	call	SENDUART	;	send to LCD
;				and the set of our of the internet (see
stop	goto	stop		; word result of 0x93FA is in accumh/accu
-			==:	
; calcu	liate CRC o	f input byte		
; CDC16				
CRC16	mo1	annahr	~	are the input character
	movwf	savchr		save the input character
	movwf			load data register
	movlw	.8		setup number of bits to test
1	movwf	j	;	save to incrementor
_loop				
	clrc	• · · -		clear carry for CRC register shift
	rrf	datareg,f	;	perform shift of data into CRC register
		-		
	rrf	accumh, f	;	
		-	; ;	skip jump if if carry

notset	goto movlw xorwf movlw xorwf	_notset polyL accuml,F polyH accumh,F		
	decfsz	J/-	; decrement bit counter	
	goto		; loop if not complete	
	movfw return		; restore the input character ; return to calling routine	
;======			, return to carring routine	-
; USER	SUPPLIED	Serial port tra	ansmit routine	
;	 RT			•
	return		; put serial xmit routine here	
;======	string s	======================================		:
; Lest	string s	corage		
,	org	0100h		
;				
InputSt				
	addwf dt	PCL, f 7h, 10h, "This is		
	al	/11,1011,"11115 18	s a lest. ",0	
•				
; :======				

Algorithm 4: "Visual Basic" Table Implementation

Visual BASIC has its own challenges as a language (such as initializing static arrays), and it is also challenging to use Visual BASIC to work with "binary" (arbitrary length character data possibly containing nulls—such as the "data" portion of the CFA533 packet) data. This routine was adapted from the C table implementation. The complete project can be found in our forums.

```
'This program is brutally blunt. Just like VB. No apologies.
'Written by Crystalfontz America, Inc. 2004 http://www.crystalfontz.com
'Free code, not copyright copyleft or anything else.
'Some visual basic concepts taken from:
'http://www.planet-source-code.com/vb/scripts/ShowCode.asp?txtCodeId=21434&lngWId=1
'most of the algorithm is from functions in 633 WinTest:
https://www.crystalfontz.com/product/633WinTest#docs
'Full zip of the project is available in our forum:
http://www.crystalfontz.com/forum/showthread.php?postid=9921#post9921
Private Type WORD
   Lo As Byte
  Hi As Byte
End Type
Private Type PACKET STRUCT
   command As Byte
   data length As Byte
   data(22) As Byte
   crc As WORD
End Type
Dim crcLookupTable(256) As WORD
Private Sub MSComm OnComm()
'Leave this here
End Sub
'My understanding of visual basic is very limited--however it appears that there is no way
'to initialize an array of structures. Nice language. Fast processors, lots of memory, big
'disks, and we fill them up with this . . this . . this . . STUFF.
Sub Initialize_CRC_Lookup_Table()
```



crcLookupTable(0).Lo = &H0 crcLookupTable(0).Hi = &H0 'For purposes of brevity in this data sheet, I have removed 251 entries of this table, the 'full source is available in our forum: http://www.crystalfontz.com/forum/showthread.php?postid=9921#post9921 crcLookupTable(255).Lo = &H78 crcLookupTable(255).Hi = &HF End Sub 'This function returns the CRC of the array at data for length positions Private Function Get Crc(ByRef data() As Byte, ByVal length As Integer) As WORD Dim Index As Integer Dim Table Index As Integer Dim newCrc As WORD newCrc.Lo = &HFFnewCrc.Hi = &HFF For Index = 0 To length - 1 'exclusive-or the input byte with the low-order byte of the CRC register 'to get an index into crcLookupTable Table Index = newCrc.Lo Xor data(Index) 'shift the CRC register eight bits to the right newCrc.Lo = newCrc.Hi newCrc.Hi = 0' exclusive-or the CRC register with the contents of Table at Table Index newCrc.Lo = newCrc.Lo Xor crcLookupTable(Table Index).Lo newCrc.Hi = newCrc.Hi Xor crcLookupTable(Table Index).Hi Next Index 'Invert & return newCrc Get Crc.Lo = newCrc.Lo Xor &HFF Get Crc.Hi = newCrc.Hi Xor &HFF End Function Private Sub Send Packet (ByRef packet As PACKET STRUCT) Dim Index As Integer 'Need to put the whole packet into a linear array 'since you can't do type overrides. VB, gotta love it. Dim linear array(26) As Byte linear array(0) = packet.command linear_array(1) = packet.data_length For Index = 0 To packet.data length - 1 linear array(Index + 2) = packet.data(Index) Next Index packet.crc = Get_Crc(linear_array, packet.data_length + 2)
'Might as well move the CRC into the linear array too linear array(packet.data length + 2) = packet.crc.Lo linear array(packet.data length + 3) = packet.crc.Hi 'Now a simple loop can dump it out the port. For Index = 0 To packet.data length + 3 MSComm.Output = Chr(linear array(Index)) Next Index End Sub

Algorithm 5: "Java" Table Implementation

This code was posted in our forum by user "norm" as a working example of a Java CRC calculation.

```
public class CRC16 extends Object
{
    public static void main(String[] args)
    {
        byte[] data = new byte[2];
        // hw - fw
        data[0] = 0x01;
        data[1] = 0x00;
        System.out.println("hw -fw req");
```



```
System.out.println(Integer.toHexString(compute(data)));
  // ping
  data[0] = 0x00;
  data[1] = 0x00;
  System.out.println("ping");
  System.out.println(Integer.toHexString(compute(data)));
  // reboot
  data[0] = 0x05;
  data[1] = 0 \times 00;
  System.out.println("reboot");
  System.out.println(Integer.toHexString(compute(data)));
  // clear lcd
  data[0] = 0x06;
  data[1] = 0 \times 00;
  System.out.println("clear lcd");
  System.out.println(Integer.toHexString(compute(data)));
  // set line 1
  data = new byte[18];
  data[0] = 0x07;
  data[1] = 0x10;
  String text = "Test Test Test ";
 byte[] textByte = text.getBytes();
  for (int i=0; i < text.length(); i++) data[i+2] = textByte[i];</pre>
  System.out.println("text 1");
  System.out.println(Integer.toHexString(compute(data)));
private CRC16()
private static final int[] crcLookupTable =
  0x00000,0x01189,0x02312,0x0329B,0x04624,0x057AD,0x06536,0x074BF,
  0x08C48,0x09DC1,0x0AF5A,0x0BED3,0x0CA6C,0x0DBE5,0x0E97E,0x0F8F7,
  0x01081,0x00108,0x03393,0x0221A,0x056A5,0x0472C,0x075B7,0x0643E,
  0x09CC9,0x08D40,0x0BFDB,0x0AE52,0x0DAED,0x0CB64,0x0F9FF,0x0E876,
  0x02102,0x0308B,0x00210,0x01399,0x06726,0x076AF,0x04434,0x055BD,
  0x0AD4A,0x0BCC3,0x08E58,0x09FD1,0x0EB6E,0x0FAE7,0x0C87C,0x0D9F5,
  0x03183,0x0200A,0x01291,0x00318,0x077A7,0x0662E,0x054B5,0x0453C,
  0x0BDCB,0x0AC42,0x09ED9,0x08F50,0x0FBEF,0x0EA66,0x0D8FD,0x0C974,
  0x04204,0x0538D,0x06116,0x0709F,0x00420,0x015A9,0x02732,0x036BB,
  0x0CE4C,0x0DFC5,0x0ED5E,0x0FCD7,0x08868,0x099E1,0x0AB7A,0x0BAF3,
  0x05285,0x0430C,0x07197,0x0601E,0x014A1,0x00528,0x037B3,0x0263A,
  0x0DECD, 0x0CF44, 0x0FDDF, 0x0EC56, 0x098E9, 0x08960, 0x0BBFB, 0x0AA72,
  0x06306,0x0728F,0x04014,0x0519D,0x02522,0x034AB,0x00630,0x017B9,
  0x0EF4E, 0x0FEC7, 0x0CC5C, 0x0DDD5, 0x0A96A, 0x0B8E3, 0x08A78, 0x09BF1,
  0x07387,0x0620E,0x05095,0x0411C,0x035A3,0x0242A,0x016B1,0x00738,
  0x0FFCF, 0x0EE46, 0x0DCDD, 0x0CD54, 0x0B9EB, 0x0A862, 0x09AF9, 0x08B70,
  0x08408,0x09581,0x0A71A,0x0B693,0x0C22C,0x0D3A5,0x0E13E,0x0F0B7,
  0x00840,0x019C9,0x02B52,0x03ADB,0x04E64,0x05FED,0x06D76,0x07CFF,
  0x09489,0x08500,0x0B79B,0x0A612,0x0D2AD,0x0C324,0x0F1BF,0x0E036,
  0x018C1,0x00948,0x03BD3,0x02A5A,0x05EE5,0x04F6C,0x07DF7,0x06C7E,
  0x0A50A,0x0B483,0x08618,0x09791,0x0E32E,0x0F2A7,0x0C03C,0x0D1B5,
  0x02942,0x038CB,0x00A50,0x01BD9,0x06F66,0x07EEF,0x04C74,0x05DFD,
  0x0B58B,0x0A402,0x09699,0x08710,0x0F3AF,0x0E226,0x0D0BD,0x0C134,
  0x039C3,0x0284A,0x01AD1,0x00B58,0x07FE7,0x06E6E,0x05CF5,0x04D7C,
  0x0C60C,0x0D785,0x0E51E,0x0F497,0x08028,0x091A1,0x0A33A,0x0B2B3,
  0x04A44,0x05BCD,0x06956,0x078DF,0x00C60,0x01DE9,0x02F72,0x03EFB,
  0x0D68D,0x0C704,0x0F59F,0x0E416,0x090A9,0x08120,0x0B3BB,0x0A232,
  0x05AC5,0x04B4C,0x079D7,0x0685E,0x01CE1,0x00D68,0x03FF3,0x02E7A,
  0x0E70E, 0x0F687, 0x0C41C, 0x0D595, 0x0A12A, 0x0B0A3, 0x08238, 0x093B1,
  0x06B46,0x07ACF,0x04854,0x059DD,0x02D62,0x03CEB,0x00E70,0x01FF9,
  0x0F78F,0x0E606,0x0D49D,0x0C514,0x0B1AB,0x0A022,0x092B9,0x08330,
  0x07BC7,0x06A4E,0x058D5,0x0495C,0x03DE3,0x02C6A,0x01EF1,0x00F78
  };
```

```
public static int compute(byte[] data)
{
    int newCrc = 0x0FFFF;
    for (int i = 0; i < data.length; i++ )
        {
        int lookup = crcLookupTable[(newCrc ^ data[i]) & 0xFF];
        newCrc = (newCrc >> 8) ^ lookup;
        }
    return(~newCrc);
    }
}
```

Algorithm 6: "Perl" Table Implementation

This code was translated from the C version by one of our customers.

#!/usr/bin/perl

```
use strict;
```

```
my @CRC LOOKUP =
```

```
(0x00000,0x01189,0x02312,0x0329B,0x04624,0x057AD,0x06536,0x074BF,
   0x08C48,0x09DC1,0x0AF5A,0x0BED3,0x0CA6C,0x0DBE5,0x0E97E,0x0F8F7,
   0x01081,0x00108,0x03393,0x0221A,0x056A5,0x0472C,0x075B7,0x0643E,
   0x09CC9,0x08D40,0x0BFDB,0x0AE52,0x0DAED,0x0CB64,0x0F9FF,0x0E876,
   0x02102,0x0308B,0x00210,0x01399,0x06726,0x076AF,0x04434,0x055BD,
   0x0AD4A,0x0BCC3,0x08E58,0x09FD1,0x0EB6E,0x0FAE7,0x0C87C,0x0D9F5,
   0x03183,0x0200A,0x01291,0x00318,0x077A7,0x0662E,0x054B5,0x0453C,
   0x0BDCB,0x0AC42,0x09ED9,0x08F50,0x0FBEF,0x0EA66,0x0D8FD,0x0C974,
   0x04204,0x0538D,0x06116,0x0709F,0x00420,0x015A9,0x02732,0x036BB,
   0x0CE4C,0x0DFC5,0x0ED5E,0x0FCD7,0x08868,0x099E1,0x0AB7A,0x0BAF3,
   0x05285,0x0430C,0x07197,0x0601E,0x014A1,0x00528,0x037B3,0x0263A,
   0x0DECD,0x0CF44,0x0FDDF,0x0EC56,0x098E9,0x08960,0x0BBFB,0x0AA72,
   0x06306,0x0728F,0x04014,0x0519D,0x02522,0x034AB,0x00630,0x017B9,
   0x0EF4E,0x0FEC7,0x0CC5C,0x0DDD5,0x0A96A,0x0B8E3,0x08A78,0x09BF1,
   0x07387,0x0620E,0x05095,0x0411C,0x035A3,0x0242A,0x016B1,0x00738,
   0x0FFCF, 0x0EE46, 0x0DCDD, 0x0CD54, 0x0B9EB, 0x0A862, 0x09AF9, 0x08B70,
   0x08408,0x09581,0x0A71A,0x0B693,0x0C22C,0x0D3A5,0x0E13E,0x0F0B7,
   0x00840,0x019C9,0x02B52,0x03ADB,0x04E64,0x05FED,0x06D76,0x07CFF,
   0x09489,0x08500,0x0B79B,0x0A612,0x0D2AD,0x0C324,0x0F1BF,0x0E036,
   0x018C1,0x00948,0x03BD3,0x02A5A,0x05EE5,0x04F6C,0x07DF7,0x06C7E,
   0x0A50A,0x0B483,0x08618,0x09791,0x0E32E,0x0F2A7,0x0C03C,0x0D1B5,
   0x02942,0x038CB,0x00A50,0x01BD9,0x06F66,0x07EEF,0x04C74,0x05DFD,
   0x0B58B,0x0A402,0x09699,0x08710,0x0F3AF,0x0E226,0x0D0BD,0x0C134,
   0x039C3,0x0284A,0x01AD1,0x00B58,0x07FE7,0x06E6E,0x05CF5,0x04D7C,
   0x0C60C, 0x0D785, 0x0E51E, 0x0F497, 0x08028, 0x091A1, 0x0A33A, 0x0B2B3,
   0x04A44,0x05BCD,0x06956,0x078DF,0x00C60,0x01DE9,0x02F72,0x03EFB,
   0x0D68D,0x0C704,0x0F59F,0x0E416,0x090A9,0x08120,0x0B3BB,0x0A232,
   0x05AC5,0x04B4C,0x079D7,0x0685E,0x01CE1,0x00D68,0x03FF3,0x02E7A,
   0x0E70E,0x0F687,0x0C41C,0x0D595,0x0A12A,0x0B0A3,0x08238,0x093B1,
   0x06B46,0x07ACF,0x04854,0x059DD,0x02D62,0x03CEB,0x00E70,0x01FF9,
   0x0F78F,0x0E606,0x0D49D,0x0C514,0x0B1AB,0x0A022,0x092B9,0x08330,
   0x07BC7,0x06A4E,0x058D5,0x0495C,0x03DE3,0x02C6A,0x01EF1,0x00F78);
#
  our test packet read from an enter key press over the serial line:
    type: 80
#
                   (key press)
#
    data length: 1
                       (1 byte of data)
#
    data = 5
my $type: '80';
my $length = '01';
my $data = '05';
my $packet = chr(hex $type) . chr(hex $length) . chr(hex $data) ;
my $valid crc = '5584' ;
```



```
print "A CRC of Packet ($packet) Should Equal ($valid crc)\n";
my $crc = 0xFFFF ;
printf("%x\n", $crc);
foreach my $char (split //, $packet)
  # newCrc = (newCrc >> 8) ^ crcLookupTable[(newCrc ^ *bufptr++) & 0xff];
  # & is bitwise AND
    ^ is bitwise XOR
  #
  # >> bitwise shift right
$crc = ($crc >> 8) ^ $CRC_LOOKUP[($crc ^ ord($char) ) & 0xFF] ;
  # print out the running crc at each byte
  printf("%x\n", $crc);
# get the complement
$crc = ~$crc ;
$crc = ($crc & 0xFFFF) ;
# print out the crc in hex
printf("%x\n", $crc);
```

Algorithm 7: For PIC18F8722 or PIC18F2685

This code was written by customer Virgil Stamps of ATOM Instrument Corporation for our CFA635 module.

```
; CRC Algorithm for CrystalFontz CFA-635 display (DB535)
; This code written for PIC18F8722 or PIC18F2685
; Your main focus here should be the ComputeCRC2 and
; CRC16 routines
ComputeCRC2:
      movlb
            RAM8
      movwf dsplyLPCNT
                         ;w has the byte count
nxt1 dsply:
      movf
             POSTINC1,w
             CRC16
      call
      decfsz dsplyLPCNT
      goto
             nxt1 dsply
      movlw
                           ; shift accumulator 16 more bits
             .0
             CRC16
      call
      movlw
            .0
      call
             CRC16
             dsplyCRC,F
                           ; invert result
      comf
      comf
             dsplyCRC+1,F
      return
CRC16 movwf:
      dsplyCRCData
                           ; w has byte to crc
      movlw
             .8
             dsplyCRCCount
      movwf
_cloop:
      bcf
             STATUS, C
                           ; clear carry for CRC register shift
             dsplyCRCData,f ; perform shift of data into CRC
      rrcf
                           ;register
             dsplyCRC,F
      rrcf
      rrcf
             dsplyCRC+1,F
      btfss
             STATUS,C
                         ; skip jump if carry
                          ; otherwise goto next bit
      goto
              notset
      movlw
             0x84
      xorwf
             dsplyCRC,F
```

movlw 0x08 ; XOR poly mask with CRC register xorwf dsplyCRC+1,F notset: decfsz dsplyCRCCount, F ; decrement bit counter ; loop if not complete bra cloop return ; example to clear screen dsplyFSR1_TEMP equ 0x83A ; 16-bit save for FSR1 for display equ 0x83C ; 16-bit CRC (H/L) equ 0x83E ; 8-bit save for display message dsplyCRC dsplyLPCNT ; length - CRC dsplyCRCData equ 0x83F ; 8-bit CRC data for display use dsplyCRCCount equ 0x840 ; 8-bit CRC count for display use SendCount equ 0x841 ; 8-bit byte count for sending to ; display equ 0x8C0 ; 32-byte receive buffer for RXBUF2 ; Display 0x8E0 ; 32-byte transmit buffer for TXBUF2 equ ; Display ;------ClearScreen: movlb RAM8 movlw .0 movwf SendCount movlw **0xF3** ; seed ho for CRC calculation movwf dsplyCRC movlw 0x21movwf dsplyCRC+1 call ClaimFSR1 ; seen lo for CRC calculation movlw 0x06 movwf TXBUF2 LFSR FSR1, TXBUF2 movf SendCount,w movwf TXBUF2+1 ; message data length call BMD1 goto SendMsg ; send message via interrupt routine. The code is made complex due ; to the limited FSR registers and extended memory space used ; example of sending a string to column 0, row 0 SignOnL1: call ClaimFSR1 lfsr FSR1,TXBUF2+4 ; set data string position SHOW CORO, BusName ; move string to TXBUF2 movlw .2 ; addwf SendCount movff SendCount,TXBUF2+1 ; insert message data length call BuildMsgDSPLY call SendMsg return ; BuildMsgDSPLY used to send a string to LCD ;------BuildMsgDSPLY: movlw 0xF3 dsplyCRC ; seed hi for CRC calculation movwf movlw 0x21 ; seed lo for CRC calculation movwf dsplyCRC+1 ; point at transmit buffer LFSR FSR1, TXBUF2 0x1F movwf TXBUF2 ; command to send data to LCD ; insert command byte from us to ; CFA-635 movlw .2 BMD1

ddwf SendCount,w ; + overhead ComputeCRC2 ; compute CRC of transmit message call movf dsplyCRC+1,w movwf POSTINC1 ; append CRC byte movf dsplyCRC,w movwf POSTINC1 ; append CRC byte return SendMsg: call ReleaseFSR1 FSR0,TXBUF2 LFSR movff FSR0H, irptFSR0 movff FSR0L, irptFSR0+1 ; save interrupt use of FSR0 movff SendCount,TXBUSY2 bsf PIE2, TX2IE ; set transmit interrupt enable ; (bit 4) return ; macro to move string to transmit buffer SHOW macro src, stringname call src MOVLF upper stringname, TBLPTRU MOVLF high stringname, TBLPTRH MOVLF low stringname, TBLPTRL call MOVE STR endm MOVE STR: tblrd *+ movf TABLAT,w bz ms1b POSTINC1 movwf incf SendCount MOVE_STR goto ms1b: return

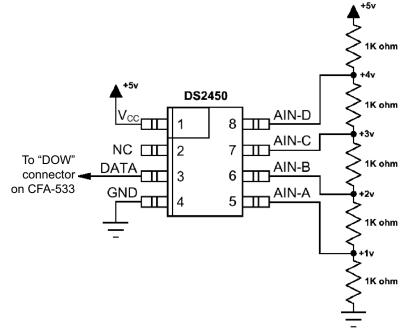


APPENDIX C: CONNECTING A DS2450 1-WIRE QUAD A/D CONVERTER

This appendix describes a simple test circuit that demonstrates how to connect a Dallas Semiconductor DS2450 4channel ADC to the CFA-533's DOW (Dallas One Wire) connector. It also gives a sample command sequence to initialize and read the ADC.

Up to 32 DOW devices can be connected to the CFA-533. In this example the DS2450 appears at device index 0. Your software should query the connected devices using command <u>18 (0x12): Read DOW Device Information (Pg. 43)</u> to verify the locations and types of DOW devices connected in your application.

Please refer to the <u>DS2450 Data Sheet</u> and the description for command <u>20 (0x14): Arbitrary DOW Transaction (Pg. 45)</u> more information.



Appendix C Figure 1. Test Circuit Schematic

Start 633WinTest (works with CFA-533) and open the Packet Debugger dialog.

Select Command 20 = Arbitrary DOW Transaction, then paste each string below into the data field and send the packet. The response should be similar to what is shown.

//Write 0x40 (=64) to address 0x1C (=28) to leave analog circuitry on //(see page 6 of the data sheet) <command 20> \000\002\085\028\000\064 //16 bit "i-button" CRC + 8-bit "DOW" CRC <response> C=84(d=0):2E,05,22 //Consult "i-button" docs to check 16-bit CRC //DOW CRC is probably useless for this device. //Write all 8 channels of control/status (16 bits, 5.10v range) <command 20> \000\002\085\008\000\000 // address = 8, channel A low
<response> C=84(d=0):6F,F1,68 // 16-bits, output off <command 20> \000\002\085\009\000\001 // address = 9, channel A high <response> C=84(d=0):FF,F1,AB // no alarms, 5.1v <command 20> \000\002\085\010\000\000 // address = 10, channel B low // 16-bits, output off <response> C=84(d=0):CE,31,88 <command 20> \000\002\085\011\000\001 // address = 11, channel B high <response> C=84(d=0):5E,31,4B // no alarms, 5.1v <command 20> \000\002\085\012\000\000 // address = 12, channel C low // 16-bits, output off <response> C=84(d=0):2E,30,A3 <command 20> \000\002\085\013\000\001 // address = 13, channel C high <response> C=84(d=0):BE,30,60 // no alarms, 5.1v <command 20> \000\002\085\014\000\000 // address = 14, channel D low <response> C=84(d=0):8F,F0,43 // 16-bits, output off <command 20> \000\002\085\015\000\001 // address = 15, channel D high // no alarms, 5.1v <response> C=84(d=0):1F,F0,80 //Read all 4 channels of control/status (check only) <command 20> \000\010\170\008\000 <response> C=84(d=0):00,01,00,01,00,01,00,01,E0,CF,01 //Repeat next two commands for each conversion (two cycles shown) //Start conversion on all channels <command 20> \000\002\060\015\000 <response> C=84(d=0):3A,03,28 //Read all 8 channels <command 20> \000\010\170\000\000 <response> C=84(d=0):00,33,DF,64,84,96,6A,C8,5A,6B,BE //Decoded response: 0x3300 = 130561.016015625 volts (channel A) 0x64DF = 258232.009541321 volts (channel B) 0x9684 = 385322.998553467 volts (channel C) 0xC86A = 513063.992623901 volts (channel D) //Start conversion on all channels <command 20> \000\002\060\015\000 <response> C=84(d=0):3A,03,28 //Read all 8 channels <command 20> \000\010\170\000\000 <response> C=84(d=0):6B,33,B2,64,97,96,42,C8,0F,C9,0A //Decoded response: 0x336B = 131631.024342346 volts (channel A) 0x64B2 = 257782.006039429 volts (channel B) 0x9697 = 385513.000032043 volts (channel C) 0xC842 = 512663.989511108 volts (channel D)